An Interactive Proof Assistant for Linear Logic

by

Maksim Trifunovski

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“When you want something, all the universe conspires in helping you to achieve it.”

Paulo Coelho, The Alchemist
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Abstract

Building formal proofs is made easier by tools called proof assistants. In this thesis we present the process of building a proof assistant for propositional intuitionistic linear logic. Linear logic is a refinement of classical and intuitionistic logic which puts its main focus on the role of its formulas as resources. While the consumption of formulas as if they are resources is a big advantage of linear logic that other logics do not offer, it is also a burden when trying to build proofs. Resource allocation in rules like Tensor Right is a difficult task since we need to predict where resources are going to be used by the rest of the proof before building it. Previous work by Hodas and Miller presents a way of using Input-Output contexts to work around this issue. But because we are building a proof-assistant and not an automated theorem prover, we need to allow the user to be able to switch between goals at any time, and be able to construct the proof in any order they want, so we cannot solve the problem with such contexts. We tackle this problem by allowing unbounded context growth when moving up the proof derivation tree, and instead allowing terms to only use variables from a given resources multiset which is a subset of the whole context. These subsets then have to satisfy a given set of equations that make them suitable for simulating context splittings and changes. In order to allow for incremental proof construction we use meta variables to stand for incomplete terms and modal contexts to store said variables, which builds on previous work by Nanevski et al. We define two sequent calculi, a base one, and one that represents the implementation. We present a cut admissibility proof that
proves that our base sequent calculus is consistent, as well as a theorem which shows that every proof in the implementation calculus, has a proof in the base calculus as well.
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Abstract

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1. Introduction

1.1. Background.

1.1.1. Proof assistants.

A proof assistant, also called an interactive theorem prover is a piece of software made to assist a human user with the development of formal proofs. These tools usually come with some sort of interactive proof editor, with which the user can guide the search for proofs. The computer helps by providing details and sometimes steps on how to advance the search.

The history of proof assistants goes back to the early 70s when Milner presented LCF (Logic for Computable Functions), which is a proof-checking program proposed by Dana Scott in 1969. [7] The program was defined with the goal of allowing users to interactively generate formal proofs about computable functions and functionals, while helping them with a subgoaling facility and a powerful simplification mechanism. LCF opened the doors for many new proof assistants.

Coq is a proof assistant which supports dependent types, uses metavariables for proof construction, and was used to create a surveyable proof of the four color theorem.[3] Agda, a dependently typed functional programming language and a proof assistant, was developed by Norell [9] and also heavily relies on metavariables. In Agda we can write functions like:

\[
\text{add} : N \rightarrow N \rightarrow N \\
\text{add} \ x \ y = ?
\]
In this function definition, the ’?’ stands for a metavariable. When interacting with this metavariable, Agda will show the user the expected type and allow the user to refine the metavariable (replace it with another term). By using metavariables, a proof assistant allows for incremental program construction.

Proof assistants are becoming increasingly more popular in both the Mathematics and Computer Science communities, as they help users substantially when building proofs. The proof assistant can first give the user the general structure of a proof, and help the user see what the smaller components of the proof that need to be completed are. For each of these smaller components, the proof assistant will try to offer the user as much valuable information possible, like types and variables available, which further helps advance the proof construction. Probably the most useful characteristic of proof assistants is fast proof checking, something that would take many tedious rounds of human checks.

1.1.2. *Sequent Calculus.*

A formal system is a well-defined system which is made up of the following:

1. A finite set of symbols used in the construction of formulas.
2. A grammar which shows how the formulas are constructed out of the symbols.
3. A set of axioms.

Sequent calculus is a family of formal systems which share a particular style of inference and properties. The first such systems were introduced by Gerhard Gentzen in 1934/1935.[1] With their introduction Gentzen also introduced his ”Main Theorem”, now known as the cut-elimination theorem, which has many consequences, one of which is consistency of the system.
In a Gentzen style sequent calculus, every line is a conditional theorem with zero or more conditions on the left and zero or more asserted propositions on the right. A sequent is an object of the form
\[ A_1, \ldots, A_n \vdash B_1, \ldots, B_m \]
where the formulas on the left of \( \vdash \) are called the antecedents, and the formulas on the right are called consequents. Each of \( A_i, B_j \) is a formula, and \( n, m \geq 0 \). We usually write \( \Gamma \) for the set of all antecedents.

An inference rule now is an object which contains of zero or more premises and one conclusion, where both the premises and the conclusion are sequents. A proof is a derivation tree where the nodes are inference rules and the leafs are axioms. We give as an example the proof of the sequent \( A, B \vdash A \land B \) in intuitionistic logic.

\[
\frac{A, B \vdash A}{A, B \vdash A \land B} \quad \left( A \in A, B \right) \quad \frac{A, B \vdash B}{A, B \vdash A \land B} \quad \left( B \in A, B \right) \quad \frac{}{A, B \vdash A \land B} \quad \rightarrow \quad \land_R
\]

1.1.3. Linear Logic.

Linear logic is a substructural logic proposed by Jean-Yves Girard as a refinement of classical and intuitionistic logic.[2] Ideas from linear logic have been influential in fields such as programming languages, game semantics, quantum physics and linguistics primarily because of its emphasis on resource-boundedness, duality and interaction. Contrary to classical and intuitionistic logic, we no longer have an ever-expanding collection of persistent "truths", as we now care about manipulating resources that cannot be duplicated or thrown away at will.

In classical and intuitionistic logics we deal with stable truths:
if $A$ and $A \Rightarrow B$, then $B$, but $A$ still holds.

In linear logic such a proof would consume both $A$ and $A \Rightarrow B$ in the process. Since linear logic is called the logic of resources, we have to introduce a new sort of implication, called linear implication ($\rightarrow$). Now if we had $1$ and a discount coupon that allows us to buy a lollipop for $1$, we could buy the lollipop, but in the process we will get rid of both the $1$ and the coupon, hence use up all of our resources. We can display the proof as follows:

\[
\frac{\text{ax}}{1 \vdash 1} \quad \frac{L \vdash L}{\text{ax}} \quad \frac{1, 1 \rightarrow L \vdash L}{\rightarrow_R}
\]

The proof uses the $\rightarrow_R$ inference rule which says that if our resources are $\Gamma, \Delta, A \rightarrow B$, and from $\Gamma$ we can prove $A$ while from $\Delta, B$ we can prove $C$, then we can prove $C$ from $\Gamma, \Delta, A \rightarrow B$.

Linear logic also introduces two conjunctions, $\otimes$ (times) and $\&$ (with). Both of them express the availability of two actions, but in the case of $\otimes$ we have the resources to do both, while in the case of $\&$ we only have the resources to do one, and we get to choose which one. Consider the following example:

\begin{align*}
A &: \text{spend } \$ 1, \\
B &: \text{buy a lollipop} \\
C &: \text{buy chewing gum}
\end{align*}

An action of type $A$ will be removing $\$1$ from our wallet. An action of type $A \rightarrow B$ means spending $\$1$ in order to get a lollipop. Given an action of type $A \rightarrow B$ and an action of type $A \rightarrow C$, there is no way to form an action of type $A \rightarrow (B \otimes C)$, since $\$1$ is not enough resources to get both a lollipop and a piece of gum. In order to get both we would need $A \otimes A$ as our resources, and the proof follows below.
To express choice of one action between two, without giving us the freedom to choose, linear logic uses $\oplus$ (plus). In terms of computer science, the distinction $\&/\oplus$ corresponds to the distinction outer/inner non-determinism.

Linear logic has a second disjunction, "$\&\&$ (par) which is the dual of "$\otimes$", and expresses a dependency between two types of actions. We can read $A \&\& B$ as either $A \perp \vdash B$ or as $B \perp \vdash A$, i.e. "$\&\&$ is a symmetric form of "$\rightarrow$".

The linear negation which we have just mentioned above, behaves like transposition in linear algebra, i.e. it expresses a duality:

$$\text{action of type } A = \text{reaction of type } A^\perp$$

The main property of linear negation is that $A^{\perp\perp}$ can be identified with $A$ just like in classical logic.

Intuitionistic linear logic is the intuitionistic restriction of linear logic. The sequent calculus of ILL is obtained from the two-sided sequent calculus of linear logic by constraining sequents to have exactly one formula on the right-hand side $\Gamma \vdash A$. The connectives $\&\&, \perp$ and $?$ are not available anymore, but linear implication $\rightarrow$ is. The two example proofs we displayed above were produced in this sequent calculus.

1.1.4. *Curry-Howard correspondence*.
1. INTRODUCTION

The Curry-Howard correspondence, also called the Curry-Howard isomorphism, represents the direct relationship between computer programs and mathematical proofs. [6] Applied to a sequent calculus it maps the right introduction rules on the logic side to constructors of code on the programming side, left introduction rules to constructors of evaluation stacks and cut elimination to reduction in a form of abstract machine.

We apply the Curry-Howard correspondence to an enriched subset of intuitionistic linear logic with metavariables, in order to get the sequent calculus in Figure 13.

1.2. Current work.

Inspired by the power of modern proof assistants like Agda and Coq, the research project which this thesis is based on was undertaken with a goal of formulating a framework that can be used to implement a proof assistant based on many different logics.

We chose to build a proof assistant for propositional intuitionistic linear logic, so we enriched its sequent calculus with modal contexts and metavariables and then applied the Curry-Howard correspondence to it to get terms for each type, and present that calculus as our base logical calculus.

Dealing with linear logic introduces issues that do not appear when building proof assistants for other logics. One such issue is resource allocation during rules that split the context of variables. To solve this we decide to let contexts grow unbounded while moving up the derivation tree, while introducing resource multisets, which act as subsets of the contexts under which they operate, but also satisfy a given set of equations.
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Using metavariables helps us construct a proof step by step, by acting as placeholders for terms we have not built yet. We prove that our system is consistent by providing a cut admissibility proof, and then we provide an implementation calculus which mirrors it.

In our implementation calculus we introduce resource variables which show up in the place of resource multisets. We have a resource restrictions context which contains the restrictions that each variable has to satisfy. Because we keep this context consistent, it can also identify resource multisets that should show up in the locations of the resources variables, when we are converting a proof from this calculus to the base one. We came up with this implementation because the main idea of a proof-assistant is to build the proof of a theorem in any order the user desires. Such a process is not feasible when using Input-Output contexts (which prove the left-most branch of the proof with a subset of all resources, and then provide the output resources to the rest of the branches of the proof), nor is it efficient to split linear contexts, since a lot of decisions on resource allocation would have to be made beforehand. In our implementation we allow all goals to use all possible unused resources at any time, and as soon as a resource has been used in any of the linked goals, we remove it from the available resources for the other goals linked with our primary one. The reader can find the implementation at https://github.com/trifunovski/Janet.

We provide a theorem that we can convert any proof from the implementation calculus under a consistent restrictions context to a proof in the base calculus.

In the conclusion we present our future ideas for how this proof assistant can be improved, and how the framework can be used to build other proof assistants.
1.3. Related work.

Nanevski et al. present a Contextual Modal Type Theory [8]. They provide a sequent calculus where judgments have 2 types of contexts, a context of propositions and a modal context of metavariables. Then they prove admissibility of cut for both contexts. They continue to extend their type theory with dependent types and talk about an implementation of meta-variables in logical frameworks. The work in this thesis is based on the work by Nanevski et al.

Shack-Nielsen and Schürman present a Linear Contextual Modal Type Theory that builds on the work by Nanevski et al. [10] They provide a type theory for a subset of linear logic enriched with modal contexts and metavariables. The subset they choose to work with differs from the one considered in this thesis, but it also tackles the issue of assigning specific resources to different parts of the proof. They use linear contexts which get split in order to deal with resource allocation. We instead let contexts grow unbounded while using resource multisets to deal with resource allocation. A contextual modal substitution (or refining a goal) is also presented.

In his PhD Thesis [4], Hodas presents the theory and design of a logic programming language based on linear logic. Hodas also uses Intuitionistic Linear Logic but works towards creating a goal-directed proof-search program, which tries to find a proof of a goal without the help of human interaction. Hodas encounters similar challenges to ours, with the main one being resource management. Hodas notes that these issues can cripple a naive implementation of this logic, hence he proposes an implementation that circumvents these problems by delaying some choices in the proof search.
This model of resource consumption was first displayed in an article by Hodas and Miller [5]. They present a so-called IO-context, in which $I - O \equiv \Gamma$ and if $A$ is a goal formula then $I\{A\}O$ is provable if and only if $\Gamma \vdash A$ has a proof. This makes finding a proof for a tensor goal easy, since we use up as many of the resources as needed in proving the first type, and then try to find a proof of the second type using the rest of the resources, and saves us from making a decision on which resources go where upfront. Because we are building a proof-assistant and not an automated theorem prover, we need to allow the user to be able to switch between goals at any time, and be able to construct the proof in any order they want. In order to do that we use resource variables which at any point can identify an upper bound resources multiset. This multiset tells us what variables we can use in the current branch of our proof. Since the resource variables are linked using restriction equations, using up variables in one, removes those variables from the upper bound multiset of another.

This thesis drew a lot of inspiration from Agda, a proof assistant designed by Norell in his PhD Thesis [9]. The idea of using metavariables to stand for parts of the term that still haven’t been built is being used heavily in Agda, as it allows for incremental proof construction.
2. Janet: An Interactive Theorem Prover

Because of the Curry-Howard isomorphism, the equivalent of a proof of a theorem in propositional linear logic is a construction of a term that has the type equivalent to the right-hand side of the theorem, using as resources variables which have types as the left-hand side of the theorem.

Therefore building a proof in Janet starts by the user entering their context of variables with their types. [Figure 1]

```
Enter the context:
x : A , y : B
```

**Figure 1.** Program start

The next step is to enter the type which is equivalent to the right-hand side of the theorem. [Figure 2]

```
Enter the intended type of the term:
A X B
```

**Figure 2.** Specifying the type

Once the sequent has been set up, we go in a loop that follows the following steps:
1. Ask the user for a goal to work on. [Figure 3]

![Figure 3. Selecting the goal](image)

2a. Display that goal’s type and resources, as well as rules the user can use to refine it. [Figure 4]

![Figure 4. Selecting the rule to refine the goal](image)

2b. If a left rule is used, select the variable to apply it to. [Figure 5]

3. Stop if we end up with a term that doesn’t contain any new goals after applying the rule. Otherwise the old goal has been replaced by a term that contains new goals, so we loop back to 1 [Figure 6].
Once we end up with a term that doesn’t contain any more goals, we have successfully created a proof. [Figure 7].

We now present a complete run of trying to prove that $A \rightarrow B$, $A \vdash B$.

We start again by entering the context and the type we are trying to construct. [Figure 8]
We continue by trying to refine the only goal we have right now, by applying the -oleft rule which will split the context and from part of it prove $A$ and from the other part with a variable of type $B$ included, will try to prove $B$. [Figure 9]

After we have applied the -oleft, we can now choose which goal to work on. We select goal number 2 and try to provide a term of type $A$. Since we have $y : A$ in our context, and it has not been used yet, we apply the Id rule to it. [Figure 10]

We now only have the goal number 3 to work on, and its type is $B$. Since we now have $x : B$ in the resources we are allowed to use (because of the -oleft rule), we apply the Id rule to $x : B$. [Figure 11]
Finally we have a complete term without any metavariables in it, and we have used up all of the resources. [Figure 12]
3. The theory behind Janet

We define a sequent calculus with metavariables in Figure 13. A sequent consists of a metavariable context, a variable context, a resource restriction, a term and a type.

The main challenge when constructing proofs in linear logic is deciding how to split the context when applying rules like tensor right and lollipop left. One approach when proving $A \otimes B$ from $\Gamma$, is to use linear contexts, and then split $\Gamma$ into $\Gamma_1, \Gamma_2$ and prove $A$ from $\Gamma_1$ and $B$ from $\Gamma_2$. In our implementation we introduce resource multisets in our sequents which are denoted with lowercase Greek letters and represent multisets of variables. A resource multiset $\alpha$ on a context $\Gamma$ means that we have to use up exactly the resources from $\Gamma$ that are in $\alpha$ when constructing a term of the given type. Resource multisets have to satisfy restriction equations which are presented in every rule of the calculus. Therefore in our sequent calculus, the variable contexts $\Gamma$ are always growing when looking at the proofs in a bottom-up manner, and instead of splitting them, we split the resource multisets $\alpha$.

The metavariable context is a non-linear set of metavariables, where each metavariable is mapped to a context $\Gamma_0$, a restriction $\alpha_0$ and a type $A$, which means that if we were to plug in a term for a metavariable, we would need to use up exactly the resources $\alpha_0$ from $\Gamma_0$ while constructing a term of type $A$.

The two rules that deal with resource allocation are $\otimes_R$ and $-\alpha_L$. We analyze the $\otimes_R$ rule presented below:
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\[
\frac{\Delta, \Gamma \vdash \alpha_1 e_1 : A \quad \Delta, \Gamma \vdash \alpha_2 e_2 : B \quad \alpha \cong \alpha_1 \cup \alpha_2}{\Delta, \Gamma \vdash (e_1, e_2) : A \otimes B} \quad \otimes_R
\]

We define \(\cong\) as multiset equality. We need to prove \(A \otimes B\) from \(\Delta|\Gamma\) under \(\alpha\). This means that we need to construct a term of type \(A \otimes B\) using only the variables contained in \(\alpha\), and completely using all of them up. All of these variables need to also be contained in \(\Gamma\). In order to do that, we need to find a split of \(\alpha\) into \(\alpha_1\) and \(\alpha_2\) such that we are able to prove \(A\) from \(\Delta|\Gamma\) under \(\alpha_1\), and \(B\) from \(\Delta|\Gamma\) under \(\alpha_2\).

Another interesting rule to analyze is the \(MV\) rule presented below:

\[
\frac{\Delta, u|\Gamma \vdash \theta : \Gamma_0 \quad \Delta, u|\Gamma, z : A \vdash \beta e : C \quad \beta[\alpha_0[z]] \cong \alpha}{\Delta, u : [\Gamma_0]_{\alpha_0} A|\Gamma \vdash \alpha \text{ let } z \text{ be } u[\theta] \text{ in } e : C} \quad \text{MV}
\]

The metavariable rule is the most important rule in our proof assistant as it constructs terms for incomplete parts of the proof which later serve as holes (goals) that the user can refine (substitute new terms in). In order to use a variable to stand for the hole \(u\) from \(\Delta, u : [\Gamma_0]_{\alpha_0} A|\Gamma\) under \(\alpha\) in \(e : C\), we need to be able to prove the following:

1. There is a substitution \(\theta\) (which stands for a list of terms, one for each variable in \(\Gamma\)) under a resource substitution \(\gamma\), which says that from \(\Gamma\) we can get \(\Gamma_0\).
2. We can prove \(e : C\) from \(\Delta, u|\Gamma, z : A\) under \(\beta\) where \(\alpha\) is equivalent to substituting the \(\alpha_0\) goal resources under the \(\gamma\) substitution for \(z\) in \(\beta\).

3.1. Two simple proofs.

In the previous section, through Janet we showed how a proof of a linear logic theorem is constructed. We now show two such proofs in our sequent calculus. Since we are interested in how resource allocation works, we display proofs of theorems that use the \(\otimes_R\) and \(-\otimes_L\) rules.
We first prove $A, B \vdash A \otimes B$.

$$\begin{align*}
\Delta &\vdash x : A, y : B & y : B \in x : A, y : B & \vdash id \\
\Delta &\vdash x : A, y : B & y : B \vdash_y y : B & \vdash id \\
\end{align*}$$

$x, y \vdash x \sqcup y$ \quad $\otimes_R$

Now we show $A \rightarrow B, A \vdash B$.

$$\begin{align*}
y : A \in f : A \rightarrow B, y : A & \vdash id \\
x : B \in f : A \rightarrow B, y : A, x : B & \vdash id \\
\Delta &\vdash f : A \rightarrow B, y : A \vdash x : B & f, y \equiv x[f[y]] & \vdash \rightarrow_L
\end{align*}$$

In order to prove that our system is consistent, we show that the cut rule is admissible. In order to prove that, we need three inversion lemmas which we prove in the next section.

### 3.2. Inversion Lemmas.

1. If $x : A \otimes B \in \Gamma$ and $\Delta|\Gamma \vdash_e e : C$, then $\exists e' \text{ s.t. } \Delta|\Gamma, x_1 : A, x_2 : B \vdash_{\alpha[x_1 \cup x_2]} e' : C$.

2. If $z : 1 \in \Gamma$ and $\Delta|\Gamma \vdash_e e : C$, then $\exists e' \text{ s.t. } \Delta|\Gamma \vdash_{\alpha[z]} e' : C$.

3. If $z : A \oplus B \in \Gamma$ and $\Delta|\Gamma \vdash_e e : C$, then $\exists e', e'' \text{ s.t. } \Delta|\Gamma, x : A \vdash_{\alpha[z]} e' : C$ and $\Delta|\Gamma, y : B \vdash_{\alpha[z]} e'' : C$.

**Proof.**

We present a part of the proof of the first lemma. The proofs for the other 2 lemmas follow the same structure.

We have $x : A \otimes B \in \Gamma$.

Base cases:

$$1_R$$
\[ \Gamma ::= \cdot \mid x : A \mid \Gamma_1 \cup \Gamma_2 \]
\[ \alpha ::= \cdot \mid x \mid \alpha_1 \cup \alpha_2 \]
\[ \Delta ::= \cdot \mid u : [\Gamma_0]_{\alpha_0} A \mid \Delta_1 \cup \Delta_2 \]
\[ \gamma ::= \cdot \mid \gamma \cdot \frac{\alpha}{\alpha_i} \]

\[
\frac{\Delta \vdash * : 1}{1_R} \quad \frac{\Delta, \gamma, \frac{\alpha}{\alpha_i} \vdash t : A}{1_L} \quad \frac{x : A \in \Gamma}{\Delta \vdash x : A} \quad \text{id}
\]

\[
\frac{\Delta \vdash \alpha_1 e_1 : A \quad \Delta \vdash \alpha_2 e_2 : B \quad \alpha \equiv \alpha_1 \cup \alpha_2}{\Delta \vdash (e_1, e_2) : A \otimes B} \quad \otimes_R
\]

\[
\frac{\Delta \vdash \alpha x . t : B}{\Delta \vdash \lambda x . t : A \multimap B} \quad \leftarrow R
\]

\[
\frac{\Delta \vdash \alpha_1 e_1 : A \quad \Delta \vdash \alpha_2 e_2 : B \quad \alpha \equiv \alpha_2 \left( \frac{R_{\text{inl}}}{x} \right)}{\Delta \vdash f : A \multimap B \vdash \alpha_1 t : A \quad \Delta \vdash f, x : B \vdash \alpha_2 e : C}{\Delta \vdash f, x : A \multimap B \vdash \alpha t : C} \quad \leftarrow L
\]

\[
\frac{\Delta \vdash \alpha \vdash t : A}{\Delta \vdash \alpha \vdash \text{inl}(t) : A \oplus B} \quad \oplus_{R_1} \quad \frac{\Delta \vdash \alpha \vdash t : B}{\Delta \vdash \alpha \vdash \text{inr}(t) : A \oplus B} \quad \oplus_{R_2}
\]

\[
\frac{\Delta \vdash \alpha \vdash e_1 : C \quad \Delta \vdash \alpha \vdash e_2 : C}{\Delta, \gamma \vdash \text{case } z \text{ of inl}(x) = e_1, \text{inr}(y) = e_2 : C} \quad \oplus_L
\]

\[
\frac{\Delta \vdash \alpha \vdash e_1 : A \quad \Delta \vdash \alpha \vdash e_2 : B}{\Delta, \gamma \vdash \alpha < e_1, e_2 > : A \& B} \quad \&_R
\]

\[
\frac{\Delta, \gamma \vdash z : A \& B, x : A \vdash e : C \quad \alpha \equiv \alpha' \left( \frac{z}{x} \right)}{\Delta, \gamma \vdash z : A \& B \vdash \alpha \vdash < x, _ > : B \text{ in } e : C} \quad \&_{L_1}
\]

\[
\frac{\Delta, \gamma \vdash z : A \& B, x : B \vdash e : C \quad \alpha \equiv \alpha' \left( \frac{z}{x} \right)}{\Delta, \gamma \vdash z : A \& B \vdash \alpha \vdash <, x > : A \text{ in } e : C} \quad \&_{L_2}
\]

\[
\Delta, u \vdash \theta : \Gamma_0 \quad \Delta, u \vdash \Gamma, z : A \vdash \beta e : C \quad \beta' \left( \frac{\alpha_0[z]}{x} \right) \equiv \alpha \quad \text{MV}
\]

Figure 13. Linear Logic Sequent Calculus with Metavariables
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\[
\Delta|\Gamma \vdash \ast : 1^R
\]

Then since \( \cdot \cong \cdot x_1 \cup x_2 \) and we can weaken \( \Gamma \) we have

\[
\Delta|\Gamma, x_1 : A, x_2 : B \vdash x_1 \cup x_2 \ast : 1^R
\]

so we are done.

\( id \)

We have 2 cases: when the variable to which \( id \) is applied is not \( x \)

\[
\frac{y : C \in \Gamma}{\Delta|\Gamma \vdash y : C} \quad id
\]

Then since \( y \neq x, y \cong y x_1 \cup x_2 \), so by just weakening \( \Gamma \), we get:

\[
\frac{y : C \in \Gamma, x_1 : A, x_2 : B}{\Delta|\Gamma, x_1 : A, x_2 : B \vdash y x_1 \cup x_2 \ast y : C} \quad id
\]

and the case where the variable to which \( id \) is applied is \( x \)

\[
\frac{x : A \otimes B \in \Gamma}{\Delta|\Gamma \vdash x : A \otimes B} \quad id
\]

Then we can construct the following term:

\[
\frac{x_1 : A \in \Gamma, x_1 : A, x_2 : B \vdash x_1 x_1 : A \quad id}{\Delta|\Gamma, x_1 : A, x_2 : B \vdash x_1 \cup x_2 : A \otimes B} \quad \otimes R
\]
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Inductive cases:

\[ \otimes R \]

\[
\frac{\Delta \vdash \alpha_1 \ v_1 : A \quad \Delta \vdash \alpha_2 \ v_2 : B}{\Delta \vdash \alpha \equiv \alpha_1 \cup \alpha_2 \ \otimes R}
\]

By applying IH twice we get \( \Delta \vdash x_1 : A, x_2 : B \vdash \alpha_1[\frac{v_1}{x_2}] \ v'_1 : A \) and \( \Delta \vdash x_1 : A, x_2 : B \vdash \alpha_2[\frac{v_1}{x_2}] \ v'_2 : B \). Now \( \alpha_1[\frac{v_1}{x_2}] \cup \alpha_2[\frac{v_1}{x_2}] \equiv (\alpha_1 \cup \alpha_2)[\frac{v_1}{x_2}] \equiv \alpha[\frac{v_1}{x_2}] \).

\[
\frac{\Delta \vdash x_1 : A, x_2 : B \vdash \alpha_1[\frac{v_1}{x_2}] \ v'_1 : A \quad \Delta \vdash x_1 : A, x_2 : B \vdash \alpha_2[\frac{v_1}{x_2}] \ v'_2 : B}{\Delta \vdash (\alpha_1 \cup \alpha_2)[\frac{v_1}{x_2}] \ v'_1, v'_2 : A \otimes B \ \otimes L}
\]

Again we deal with two cases, one when the rule is not applied to the \( x : A \otimes B \) variable:

\[
\frac{\Delta \vdash y : C \otimes D, y_1 : C, y_2 : D \vdash \alpha[\frac{y_1}{y_2}] \ e : E}{\Delta \vdash y : C \otimes D \vdash \alpha \ \otimes L}
\]

By applying IH we get \( \Delta \vdash y : C \otimes D, y_1 : C, y_2 : D, x_1 : A, x_2 : B \vdash (\alpha[\frac{y_1}{y_2}] \frac{x_1}{x_2}] \ e' : E \), and since \( y \neq x \), we have \( (\alpha[\frac{y_1}{y_2}] \frac{x_1}{x_2}] \equiv (\alpha[\frac{x_1}{y_2}] \frac{x_1}{x_2}] \). So by applying \( \otimes L \) again, we get

\[
\frac{\Delta \vdash y : C \otimes D, y_1 : C, y_2 : D, x_1 : A, x_2 : B \vdash (\alpha[\frac{y_1}{y_2}] \frac{x_1}{x_2}] \ e' : E}{\Delta \vdash y : C \otimes D \vdash \alpha[\frac{x_1}{y_2}] \frac{x_1}{x_2}] \ e' \ \otimes L}
\]

In the case that the rule is applied to the \( x : A \otimes B \) variable we have:
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\[
\frac{\Delta \vdash \alpha_{[x_1/x]} e : C}{\Delta \vdash \alpha \overset{\otimes}{L}}
\]

\[\Delta \vdash \alpha_{[\alpha_{[x_1/x]}]} e : C \quad \otimes_L \]

so since we already have \(\Delta \vdash x_1 : A, x_2 : B \vdash e : C\), we are done.

The rest of the proof is left as an exercise for the reader.

\[\square\]

3.3. Admissibility of cut.

**Theorem:**

1. If \(\Delta \vdash A\) and \(\Gamma \vdash e : B\) then \(\Delta \vdash \alpha \vdash \beta \vdash e : B\). (cut)

2. If \(\Delta \vdash \alpha \vdash A\) and \(\Gamma \vdash e \vdash e : B\) then \(\Delta \vdash \alpha \vdash e : B\). (cut!)

**Proof.**

1. We write \(l\) (left) for the derivation of \(A\) and \(r\) (right) for the derivation of \(B\). We proceed by induction on \(r\) by first showing what happens in the case that the last step of the derivation of \(r\) is a right rule. We then consider the cases where the last rule applied in the derivation of \(r\) is a left rule. In those cases, the last rule applied in the derivation of \(l\) is either the matching right rule, or any other left rule.

**Base cases:**

1. \(1_R\)

\[
\frac{\Delta \vdash \alpha \vdash A \quad \Delta \vdash x \vdash A \vdash \cdot \vdash \cdot}{\Delta \vdash \cdot \vdash e : B \quad \cdot \vdash e : B} \quad 1_R
\]

Then since \(\cdot \vdash e : B\) from \(1_R\) we have
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\[
\frac{\Delta \mid \Gamma \vdash e' : C}{\Delta \mid \Gamma \vdash \beta \Gamma, x : C \vdash \beta_1 e_1 : A, \Delta \mid \Gamma, x : C \vdash \beta_2 e_2 : B}{\Delta \mid \Gamma \vdash \beta \Gamma, (e_1, e_2) \mid \beta \Gamma \vdash \beta \Gamma \vdash \beta_1 \cup \beta_2 e_1 \mid \beta_2 e_2 : A \otimes B \quad \otimes_R}
\]

so we are done.

**id**

We get 2 cases: if the variable being cut is the one to which the *id* rule is applied:

\[
\frac{\Delta \mid \Gamma \vdash x : A \in \Gamma}{\Delta \mid \Gamma \vdash x \mid \beta \Gamma \vdash x : A \quad \text{id}}
\]

Then since \(x[\alpha] \approx \alpha\) from \(l\) we have \(\Delta \mid \Gamma \vdash e' : A\), so we are done.

and the case where the cut variable isn’t the one to which the *id* rule is applied:

\[
\frac{\Delta \mid \Gamma, y : B \vdash e' : A}{\Delta \mid \Gamma, y : B \vdash y \mid \beta \Gamma \vdash y : B \quad \text{id}}
\]

Then since \(y[\alpha] \approx y\) from \(id\) we have \(\Delta \mid \Gamma, y : B \vdash y : B\), so we are done.

Inductive cases:

We will first do all of the right rules.

\(\otimes R\)

\[
\frac{\Delta \mid \Gamma \vdash x : C \vdash \beta_1 e_1 : A, \Delta \mid \Gamma, x : C \vdash \beta_2 e_2 : B}{\Delta \mid \Gamma \vdash \beta \Gamma, (e_1, e_2) \mid \beta \Gamma \vdash \beta \Gamma \vdash \beta \Gamma \vdash \beta_1 \cup \beta_2 e_1 \mid \beta_2 e_2 : A \otimes B \quad \otimes_R}
\]

Now we can cut \(\Delta \mid \Gamma \vdash e' : C\) and \(\Delta \mid \Gamma, x : C \vdash \beta_1 e_1 : A\) to get \(\Delta \mid \Gamma \vdash e_1[\beta_1[\alpha]\Gamma] : A\), as well as \(\Delta \mid \Gamma \vdash e' : C\) and \(\Delta \mid \Gamma, x : C \vdash \beta_2 e_2 : B\) to get \(\Delta \mid \Gamma \vdash e_2[\beta_2[\alpha]\Gamma] : B\).
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e_2[e' \over x] : B. Furthermore applying the substitution \([α \over x}\] to both sides of \(β ≅ β_1 ∪ β_2\), we get \(β[α \over x] ≅ (β_1 ∪ β_2)[α \over x]\) which is equivalent to \(β[α \over x] ≅ β_1[α \over x] ∪ β_2[α \over x]\). Then applying ⊗_R we get

\[
\frac{Δ|\Gamma \vdash β_1[α \over x] e_1[e' \over x] : A \quad Δ|\Gamma \vdash β_2[α \over x] e_2[e' \over x] : B \quad β[α \over x] ≅ β_1[α \over x] ∪ β_2[α \over x]}{Δ|\Gamma \vdash (e_1[e' \over x], e_2[e' \over x]) : A ⊗ B}
\]

Now we can cut \(Δ|\Gamma \vdash α e' : C\) and \(Δ|\Gamma, x : A, y : C \vdash β_α e : B\) to get

\[
\frac{Δ|\Gamma, x : A, y : C \vdash β_α e : B \quad Δ|\Gamma, y : C \vdash λx.e : A → B}{Δ|\Gamma \vdash (λx. t[e' \over y]) : A ⊗ B}
\]

Now we can cut \(Δ|\Gamma \vdash α e' : C\) and \(Δ|\Gamma, x : A \vdash β_α e : B\) to get \(Δ|\Gamma, x : A \vdash (β ∪ x)[α \over y] e[e' \over x] : B\). Then since \(y \neq x\), \((β ∪ x)[α \over y] ≅ (β[α \over y]) ∪ x\), so by applying \(→_R\) we get

\[
\frac{Δ|\Gamma, x : A \vdash (β[α \over y]) ∪ x e[e' \over y] : B}{Δ|\Gamma \vdash λx.(t[e' \over y]) : A → B}
\]

Now we can cut \(Δ|\Gamma, x : A \vdash β_α e : A\) to get \(Δ|\Gamma \vdash β[α \over x] e[e' \over x] : A\). Then by applying \(⊕_R\) we get

\[
\frac{Δ|\Gamma, x : A \vdash β_α e : A \quad Δ|\Gamma, x : A \vdash inl(e) : A ⊕ B}{Δ|\Gamma \vdash inl(e) : A ⊕ B}
\]
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\( \oplus_{R_2} \)

\[
\frac{
\Delta \vdash \alpha \ e' : C \quad \Delta \vdash \beta \ inr(e) : \ A \oplus B
}{
\Delta \vdash \beta[\frac{x}{\alpha}] \ inr(e[\frac{x'}{x}]) : \ A \oplus B}
\]

Now we can cut \( \Delta \vdash \alpha \ e' : C \) and \( \Delta \vdash \beta \ e : B \) to get \( \Delta \vdash \beta[\frac{x}{\alpha}] \ e[\frac{x'}{x}] : B \). Then by applying \( \oplus_{R_2} \) we get

\[
\frac{
\Delta \vdash \beta[\frac{x}{\alpha}] \ e[\frac{x'}{x}] : B
}{
\Delta \vdash \beta[\frac{x}{\alpha}] \ inr(e[\frac{x'}{x}]) : \ A \oplus B}
\]

&\(_R\)

\[
\frac{
\Delta \vdash \alpha \ e' : C \quad \Delta \vdash \beta \ e_1 : A \quad \Delta \vdash \beta \ e_2 : B
}{
\Delta \vdash \beta[\frac{x}{\alpha}] \ e_1[\frac{x'}{x}] : A \land B}
\]

Now we can cut \( \Delta \vdash \alpha \ e' : C \) and \( \Delta \vdash \beta \ e_1 : A \) to get \( \Delta \vdash \beta[\frac{x}{\alpha}] \ e_1[\frac{x'}{x}] : A \), as well as \( \Delta \vdash \alpha \ e' : C \) and \( \Delta \vdash \beta \ e_2 : B \) to get \( \Delta \vdash \beta[\frac{x}{\alpha}] \ e_2[\frac{x'}{x}] : B \). Then by applying &\(_R\) we get

\[
\frac{
\Delta \vdash \beta[\frac{x}{\alpha}] \ e_1[\frac{x'}{x}] : A \quad \Delta \vdash \beta[\frac{x}{\alpha}] \ e_2[\frac{x'}{x}] : B
}{
\Delta \vdash \beta[\frac{x}{\alpha}] \ e_1[\frac{x'}{x}], e_2[\frac{x'}{x}] : A \land B}
\]

MV

\[
\Delta, u : [\Gamma]_{\alpha} \Delta \vdash \alpha \ e' : B
\]

\[
\Delta, u : [\Gamma]_{\alpha} \Delta \vdash \alpha \ e' : B
\]

\[
\Delta, u : [\Gamma]_{\alpha} \Delta \vdash \alpha \ e' : B
\]

\[
\Delta, u : [\Gamma]_{\alpha} \Delta \vdash \alpha \ e' : B
\]
Now we can weaken and then cut $\Delta, u : \Gamma \vdash \alpha : B$ and $\Delta, u : \Gamma, z : A, x : B \vdash_{\delta} e : C$ to get $\Delta, u : \Gamma, z : A \vdash_{\delta(\frac{x}{z})} e[\frac{e'}{x}] : C$, as well as $\Delta, u : \Gamma, z : A \vdash_{\delta(\frac{x}{z})} e[\frac{e'}{x}] : C$. By iterating the inductive hypothesis for each term in $\theta$, get $\Delta, u : \Gamma \vdash \gamma[\alpha x] e[\frac{e'}{x}] : \Gamma_{0}$.

Then by applying $\text{MV}$ we get

$$\Delta, u : \Gamma \vdash \gamma[\alpha x] e[\frac{e'}{x}] : \Gamma_{0}$$

If the last rule in the derivation of $r$ (right) is a left rule, we have to consider 2 separate cases. One where the cut variable is not the variable on which the last rule in the derivation of $l$ (left) is applied, and one where it is. We will first consider the cases where the variable cut is not used in the last rule of the derivation of $r$.

$$1L$$

$$\Delta | \Gamma, z : 1, x : B \vdash_{\beta(\frac{1}{z})} e : A$$

$$\Delta | \Gamma \vdash_{\alpha} e' : B$$

$$\Delta | \Gamma, z : 1, x : B \vdash_{\beta} 1 \text{ let } 1 \text{ be } z \text{ in } e : A \vdash_{1L} e[\frac{e'}{x}] : A$$

Now we can weaken and cut $\Delta | \Gamma \vdash_{\alpha} e' : B$ and $\Delta | \Gamma, z : 1, x : B \vdash_{\beta(\frac{1}{z})} e : A$ to get $\Delta | \Gamma, z : 1 \vdash_{(\beta(\frac{1}{z}))}\frac{1}{z} e[\frac{e'}{x}] : A$. We also have $(\beta(\frac{1}{z}))\frac{1}{z} \cong (\beta(\frac{1}{z}))\frac{1}{z}$, since $z \not\in \alpha$.

So by applying $1L$ we get

$$\Delta | \Gamma, z : 1 \vdash_{(\beta(\frac{1}{z}))}\frac{1}{z} e[\frac{e'}{x}] : A$$

$$\Delta | \Gamma, z : 1 \vdash_{\beta(\frac{1}{z})} \text{ let } 1 \text{ be } z \text{ in } e[\frac{e'}{x}] : A$$
$\otimes_L$

\[
\frac{\Delta|\Gamma, y : D, x : A \otimes B, x_1 : A, x_2 : B \vdash \beta_{[x_1/x_2]} e : C}{\Delta|\Gamma, y : D, x : A \otimes B \vdash \left(\beta_{[x_1/x_2]}\right)[\frac{e}{y}] : C} \quad \otimes_L
\]

Now we can weaken and then cut $\Delta|\Gamma \vdash \alpha e' : D$ and $\Delta|\Gamma, y : D, x : A \otimes B, x_1 : A, x_2 : B \vdash \beta_{[x_1/x_2]} e : C$ to get $\Delta|\Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash \left(\beta_{[x_1/x_2]}\right)[\frac{e}{y}] : C$. Now since $(\beta_{[x_1/x_2]})[\frac{e}{y}] \cong (\beta_{[x_1/x_2]})[\frac{e'}{y}]$ by applying $\otimes_L$ we get

\[
\frac{\Delta|\Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash \left(\beta_{[x_1/x_2]}\right)[\frac{e'}{y}] : C}{\Delta|\Gamma, x : A \otimes B \vdash \beta_{[x_2]} e} \quad \Delta|\Gamma, x : A \otimes B \vdash \left(\beta_{[x_1/x_2]}\right)[\frac{e'}{y}] : C \quad \otimes_L
\]

$\oslash_L$

\[
\frac{\Delta|\Gamma, y : D, f : A \rightarrow B \vdash \beta_1 t : A \quad \Delta|\Gamma, y : D, f : A \rightarrow B, x : B \vdash \beta_3 e : C}{\Delta|\Gamma, y : D, f : A \rightarrow B \vdash \beta_{[x_1/x_2]} t[\frac{e}{y}] : A} \quad \beta \cong \beta_{[x_1/x_2]} \quad \oslash_L
\]

Now we can weaken and cut $\Delta|\Gamma \vdash \alpha e' : D$ and $\Delta|\Gamma, y : D, f : A \rightarrow B \vdash \beta_{[x_1/x_2]} t[\frac{e}{y}] : A$, as well as $\Delta|\Gamma \vdash \alpha e' : D$ and $\Delta|\Gamma, y : D, f : A \rightarrow B, x : B \vdash \beta_{[x_1/x_2]} e[\frac{e'}{y}] : C$ to get $\Delta|\Gamma, f : A \rightarrow B, x : B \vdash \beta_{[x_1/x_2]} e[\frac{e'}{y}] : C$. Then by applying $\oslash_L$ we get

\[
\frac{\Delta|\Gamma, f : A \rightarrow B \vdash \beta_{[x_1/x_2]} t[\frac{e}{y}] : A \quad \Delta|\Gamma, f : A \rightarrow B, x : B \vdash \beta_{[x_1/x_2]} e[\frac{e'}{y}] : C}{\Delta|\Gamma, f : A \rightarrow B \vdash \beta_{[x_1/x_2]} t[\frac{e}{y}] : A \quad \beta \cong \beta_{[x_1/x_2]} \quad \oslash_L}
\]

$\oplus_L$

\[
\frac{\Delta|\Gamma, w : D, z : A \otimes B, x : A \vdash \beta_{[x_1/x_2]} e_1 : C \quad \Delta|\Gamma, w : D, z : A \otimes B, y : B \vdash \beta_{[x_2/y_2]} e_2 : C}{\Delta|\Gamma \vdash \alpha e' : D \quad \Delta|\Gamma, w : D, z : A \otimes B \vdash \beta_{[x_1/x_2]} \text{ case } z \text{ of } \text{inl}(x) \Rightarrow e_1, \text{inr}(y) \Rightarrow e_2 : C} \quad \oplus_L
\]

\[
\frac{\Delta|\Gamma, z : A \otimes B \vdash \beta_{[x_1/x_2]} \text{ case } z \text{ of } \text{inl}(x) \Rightarrow e_1, \text{inr}(y) \Rightarrow e_2[\frac{e}{y}] : C}{\Delta|\Gamma, z : A \otimes B \vdash \beta_{[x_1/x_2]} \text{ case } z \text{ of } \text{inl}(x) \Rightarrow e_1, \text{inr}(y) \Rightarrow e_2[\frac{e}{y}] : C} \quad \text{cut}
\]
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Now we can weaken and cut $\Delta|\Gamma, \varepsilon : D$ and $\Delta|\Gamma, w : D, z : A \oplus B, x : A \vdash_{\beta[\frac{x}{w}]} e_1 : C$ to get $\Delta|\Gamma, z : A \oplus B, x : A \vdash_{(\beta[\frac{x}{w}])[\frac{2}{w}]} e_1[\frac{w}{w}] : C$, as well as $\Delta|\Gamma, w : D, z : A \oplus B, y : B \vdash_{\beta[\frac{x}{w}]} e_2 : C$ to get $\Delta|\Gamma, z : A \oplus B, y : B \vdash_{(\beta[\frac{x}{w}])[\frac{y}{w}]} e_2[\frac{w}{w}] : C$. Since $(\beta[\frac{x}{w}])[\frac{2}{w}] \cong (\beta[\frac{x}{w}])[\frac{w}{w}]$ and $(\beta[\frac{x}{w}])[\frac{y}{w}] \cong (\beta[\frac{x}{w}])[\frac{w}{w}]$ we can apply $\oplus_L$ and get

$$\frac{\Delta|\Gamma, z : A \oplus B, x : A \vdash_{(\beta[\frac{x}{w}])[\frac{2}{w}]} e_1[\frac{w}{w}] : C}{\Delta|\Gamma, z : A \oplus B \vdash_{\beta[\frac{x}{w}]} (e_1[\frac{w}{w}] : C)} \oplus_L$$

$\&_{L_1}$

$$\frac{\beta \cong \beta'[\frac{x}{y}] \quad \Delta|\Gamma, y : D, z : A \& B \vdash_{\beta'} e : C}{\Delta|\Gamma, z : A \& B \vdash_{\beta[\frac{x}{y}]} (e[\frac{y}{y}] : C)} \&_{L_1}$$

$\Delta|\Gamma, z : A \& B \vdash_{\beta[\frac{x}{y}]} (e[\frac{y}{y}] : C)$

Now we can weaken and cut $\Delta|\Gamma, z : A \& B \vdash_{\alpha} e' : D$ and $\Delta|\Gamma, y : D, z : A \& B, x : A \vdash_{\beta'} e : C$ to get $\Delta|\Gamma, z : A \& B, x : A \vdash_{(\beta'[\frac{y}{y}])[\frac{2}{y}]} e'[\frac{y}{y}] : C$. We have $(\beta'[\frac{y}{y}])[\frac{2}{y}] \cong (\beta'[\frac{y}{y}])[\frac{y}{y}] \cong \beta[\frac{y}{y}]$ because $x \not\in \alpha$, so by applying $\&_{L_1}$ we get

$$\frac{\beta[\frac{y}{y}] \cong (\beta'[\frac{y}{y}])[\frac{y}{y}] \quad \Delta|\Gamma, z : A \& B \vdash_{(\beta'[\frac{y}{y}])[\frac{2}{y}]} e'[\frac{y}{y}] : C}{\Delta|\Gamma, z : A \& B \vdash_{\beta[\frac{y}{y}]} (e'[\frac{y}{y}] : C)} \&_{L_1}$$

$\&_{L_2}$

$$\frac{\beta \cong \beta'[\frac{x}{y}] \quad \Delta|\Gamma, y : D, z : A \& B \vdash_{\beta'} e : C}{\Delta|\Gamma, z : A \& B \vdash_{\beta[\frac{y}{y}]} (e[\frac{y}{y}] : C)} \&_{L_2}$$

$\Delta|\Gamma, z : A \& B \vdash_{\beta[\frac{y}{y}]} (e[\frac{y}{y}] : C)$

Now we can weaken and cut $\Delta|\Gamma, z : A \& B \vdash_{\alpha} e' : D$ and $\Delta|\Gamma, y : D, z : A \& B, x : B \vdash_{\beta'} e : C$ to get $\Delta|\Gamma, z : A \& B, x : B \vdash_{(\beta'[\frac{y}{y}])[\frac{2}{y}]} e'[\frac{y}{y}] : C$. We have $(\beta'[\frac{y}{y}])[\frac{2}{y}] \cong (\beta'[\frac{y}{y}])[\frac{y}{y}] \cong \beta[\frac{y}{y}]$ because $x \not\in \alpha$, so by applying $\&_{L_2}$ we get
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\[ \Delta | \Gamma, z : A \& B, x : B \vdash \beta_{[\gamma]}^{[\delta]} e_{[\gamma]}^{[\delta]} : C \quad \beta_{[\gamma]}^{[\delta]} \cong (\beta_{[\gamma]}^{[\delta]})_{[\zeta]} \]

\[ \Delta | \Gamma, z : A \& B \vdash \beta_{[\gamma]}^{[\delta]} \; \text{let} \; < \zeta, x > \; \text{be} \; z \; \text{in} \; e_{[\gamma]}^{[\delta]} : C \]

Now we need to consider the case where the cut variable is used in the last step of the derivation of \( r(\text{right}) \). In this case the last step of the derivation of \( l \), has to either be the right rule for the same operator, or any other left rule. Again we split in 2 cases: first we will prove the cases where the derivation of \( l \) ends in the right rule for the same operator, and then we will prove the cut theorem for all the left rules as last steps in the derivation of \( l \).

\[ 1R \text{ and } 1L \]

\[ 1R - \Delta | \Gamma \vdash * : 1 \]

\[ \Delta | \Gamma, z : 1 \vdash \beta_{[\gamma]}^{[\delta]} e : A \quad 1L \]

\[ \Delta | \Gamma \vdash \beta_{[\gamma]}^{[\delta]} \; \text{let} \; * \; \text{be} \; z \; \text{in} \; e_{[\gamma]}^{[\delta]} : A \quad \text{cut} \]

Now we can cut \( \Delta | \Gamma \vdash * : 1 \) and \( \Delta | \Gamma, z : 1 \vdash \beta_{[\gamma]}^{[\delta]} e : A \) to get \( \Delta | \Gamma \vdash \beta_{[\gamma]}^{[\delta]}[z] e_{[\gamma]}^{[\delta]} : A \). But since \( (\beta_{[\gamma]}^{[\delta]})_{[\zeta]} \cong \beta_{[\gamma]}^{[\delta]} \) we have \( \Delta | \Gamma \vdash \beta_{[\gamma]}^{[\delta]} e_{[\gamma]}^{[\delta]} : A \).

\[ \otimes R \text{ and } \otimes L \]

\[ \otimes R - \Delta | \Gamma \vdash_{\alpha_1} e_1 : A \quad \Delta | \Gamma \vdash_{\alpha_2} e_2 : B \quad \alpha \cong \alpha_1 \cup \alpha_2 \]

\[ \Delta | \Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash \beta \text{let} \; (x_1, x_2) \; \text{be} \; x \; \text{in} \; e : C \quad \otimes L \]

\[ \Delta | \Gamma \vdash \beta_{[\gamma]}^{[\delta]} \; \text{let} \; (x_1, x_2) \; \text{be} \; x \; \text{in} \; e_{[\gamma]}^{[\delta]} : C \quad \text{cut} \]

Now we can weaken and then cut \( \Delta | \Gamma \vdash_{\alpha_1} (e_1, e_2) : A \otimes B \) into \( \Delta | \Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash \beta_{[\gamma]}^{[\delta]} e : C \) to get \( \Delta | \Gamma, x_1 : A, x_2 : B \vdash (\beta_{[\gamma]}^{[\delta]})_{[\zeta]} e_{[\gamma]}^{[\delta]} : e_{[\gamma]}^{[\delta]} : C \). Now weaken and cut \( \Delta | \Gamma \vdash_{\alpha_1} e_1 : A \) into this to get \( \Delta | \Gamma, x_2 : B \vdash \beta_{[\gamma]}^{[\delta]} e : C \).
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\[ B \vdash ((\beta[x:f])|\alpha) \left( e[\frac{[f_1,f_2]}{x}] \right)[\frac{f_1}{x_1}] : C. \]

Finally weaken and cut \( \Delta | \Gamma \vdash_{\alpha_2} e_2 : B \) into the previous result to get \( \Delta | \Gamma \vdash ((\beta[x:f])|\alpha) \left( e[\frac{[f_1,f_2]}{x}] \right)[\frac{f_1}{x_1}] : C. \)

Now since \( ((\beta[x:f])|\alpha) \left( e[\frac{[f_1,f_2]}{x}] \right)[\frac{f_1}{x_1}] \) is equivalent to \( (\beta[\frac{f_1}{x}])|\alpha \), and now since \( x \notin \alpha \) that is equivalent to just \( \beta[\frac{f_1}{x}] \), so

\[ \Delta | \Gamma \vdash (\beta[\frac{f_1}{x}]) \left( e[\frac{[f_1,f_2]}{x}] \right)[\frac{f_1}{x_1}] : C. \]

\(- \circ_R \) and \(- \circ_L \)

\[ \Delta | \Gamma, z : A \vdash_{\alpha_{\beta_1}} e' : B \quad \Delta | \Gamma, f : A \rightarrow B \vdash_{\beta_1} t : A \quad \Delta | \Gamma, f : A \rightarrow B, x : B \vdash_{\beta_2} e : C \quad \beta \equiv \beta_2 \left[ \frac{f}{x} \right] \quad \Delta | \Gamma \vdash_{\beta_2} \left[ \frac{t}{x} \right] : C \] cut

Now we can cut \( \Delta | \Gamma \vdash_{\alpha_{\beta_1}} \lambda z. e' : A \rightarrow B \) into \( \Delta | \Gamma, f : A \rightarrow B \vdash_{\beta_1} t : A \) to get \( \Delta | \Gamma, f : A \rightarrow B, x : B \vdash_{\beta_2} e : C \) to get \( \Delta | \Gamma, f : A \rightarrow B \vdash_{\beta_2} e' \left[ \frac{t}{x} \right] : C. \) Now cut \( \Delta | \Gamma, f : A \rightarrow B \vdash_{\beta_2} \left[ \frac{t}{x} \right] : A \) into \( \Delta | \Gamma, z : A \vdash_{\alpha_{\beta_1}} e' : B \) to get \( \Delta | \Gamma \vdash_{\alpha_{\beta_1}} \left[ \frac{t}{x} \right] e' \left[ \frac{t}{x} \right] : C. \)

Now we have \( \beta[\frac{f_1}{x}] \equiv (\beta_2[\frac{f_1}{x}])|\alpha \equiv (\beta_2[\frac{f_1}{x}])|\alpha_{\beta_1}[\frac{f_1}{x}] \). So we are done.

\( \oplus_{R_1} \) and \( \oplus_{L} \)

\[ \Delta | \Gamma \vdash_{\alpha} e' : A \quad \Delta | \Gamma, z : A \cup B, x : A \vdash_{\beta} e_1 : C \quad \Delta | \Gamma, z : A \cup B, y : B \vdash_{\beta} e_2 : C \quad \Delta | \Gamma \vdash_{\beta} \left[ \frac{\left( e_1, e_2 \right)}{x} \right] : C \] cut
Now we can weaken and cut $\Delta|\Gamma \vdash_\alpha inl(e') : A \oplus B$ into $\Delta|\Gamma, z : A \oplus B, x : A \vdash_{\beta[z]} e_1 : C$ to get $\Delta|\Gamma, x : A \vdash_{(\beta[z])[\frac{\alpha}{z}]} e_1[\frac{inl(e')}{x}] : C$ We then weaken and cut $\Delta|\Gamma \vdash_\alpha e' : A$ into the previous result to get to get $\Delta|\Gamma \vdash_{((\beta[z])[\frac{\alpha}{z}])[\frac{\alpha}{y}]} (e_1[\frac{inl(e')}{x}])[\frac{e'}{y}] : C$. Now since $((\beta[z])[\frac{\alpha}{z}])[\frac{\alpha}{y}] \equiv (\beta[z])[\frac{\alpha}{z}]$, we get

$$\Delta|\Gamma \vdash_{\beta[z]} (e_1[\frac{inl(e')}{x}])[\frac{e'}{y}] : C$$

$\oplus_{R_2}$ and $\oplus_{L}$

\[
\frac{\Delta|\Gamma \vdash \alpha e' : B}{\Delta|\Gamma \vdash \alpha inl(e') : A \oplus B} \quad \frac{\Delta|\Gamma, z : A \oplus B, x : A \vdash_{\beta[z]} e_1 : C}{\Delta|\Gamma, z : A \oplus B, y : B \vdash_{\beta[y]} e_2 : C} \quad \frac{\Delta|\Gamma \vdash_{\beta[z]} (\text{case } z \text{ of } inl(x) \Rightarrow e_1, \text{inr}(y) \Rightarrow e_2)}{\Delta|\Gamma \vdash_{\beta[z]} \alpha : \text{ inr}(e') : \text{ C}} \quad \text{cut}
\]

Now we can weaken and cut $\Delta|\Gamma \vdash_{\alpha} \text{ inr}(e') : A \oplus B$ into $\Delta|\Gamma, z : A \oplus B, y : B \vdash_{\beta[y]} e_2 : C$ to get $\Delta|\Gamma, y : B \vdash_{(\beta[y])[\frac{\alpha}{y}]} e_2[\frac{\text{inr}(e')}{x}] : C$ Then we can weaken and cut $\Delta|\Gamma \vdash_{\alpha} e' : B$ into the previous result to get to get $\Delta|\Gamma \vdash_{((\beta[y])[\frac{\alpha}{y}])[\frac{\alpha}{y}]} (e_2[\frac{\text{inr}(e')}{x}])[\frac{e'}{y}] : C$. Now since $((\beta[y])[\frac{\alpha}{y}])[\frac{\alpha}{y}] \equiv (\beta[y])[\frac{\alpha}{y}]$, we get

$$\Delta|\Gamma \vdash_{\beta[z]} (e_2[\frac{\text{inr}(e')}{x}])[\frac{e'}{y}] : C$$

&$_R$ and &$_{L_1}$

\[
\frac{\Delta|\Gamma \vdash_{\alpha} e_1 : A}{\Delta|\Gamma \vdash_{\alpha} e_1 \alpha A & B} \quad \frac{\Delta|\Gamma \vdash_{\alpha} e_2 : B}{\Delta|\Gamma \vdash_{\alpha} e_2 \alpha A & B} \quad \frac{\Delta|\Gamma, z : A & B, x : A \vdash_{\beta'} e : C}{\beta \equiv \beta'[\frac{\alpha}{z}]} \quad \frac{\Delta|\Gamma, z : A & B \vdash_{\beta} \text{ let } < x, z > \leadsto \text{ be } z \text{ in } e : C}{\Delta|\Gamma \vdash_{\beta[z]} (\text{let } < x, z > \text{ be } z \text{ in } e)[\frac{<e_1, e_2>}{z}] : C} \quad \text{cut}
\]

Now we can weaken and cut $\Delta|\Gamma \vdash_{\alpha} < e_1, e_2 > : A & B$ into $\Delta|\Gamma, z : A & B, x : A \vdash_{\beta'} e : C$ to get $\Delta|\Gamma, x : A \vdash_{\beta'[\frac{\alpha}{z}]} e[\frac{<e_1, e_2>}{z}] : C$. Then we weaken and cut
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\[ \Delta \vdash_{\alpha} e_1 : A \] into the previous result to get \[ \Delta \vdash_{(\beta'[z])} (e[\frac{<e_1,e_2>}{z}])[z] : C. \]

We have \[ \beta[z] \cong (\beta'[x])[z] \cong (\beta'[z])[z] \]. So we get

\[ \Delta \vdash_{\beta[z]} (e[\frac{<e_1,e_2>}{z}])[z] : C \]

\&_R and \&_L_2

Now we consider the cases where the last step of the derivation of \( l \) is a left rule.

1. \( L \)

\[
\frac{\Delta, z : 1 \vdash_{\alpha[z]} e' : B}{\Delta, z : 1 \vdash_\alpha \text{let } * \text{ be } z \text{ in } e' : B} \quad \frac{\Delta, z : 1 \vdash_\beta e : A}{\Delta, z : 1, x : B \vdash_\beta e : A} \quad \frac{\Delta, z : 1 \vdash_\beta[z] e[\text{let } * \text{ be } z \text{ in } e'] : A}{\text{cut}}
\]
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Now since we have \( z : 1 \) in the derivation of \( \Delta|\Gamma, z : 1, x : B \vdash \beta e : A \), by the inversion lemma we get \( \Delta|\Gamma, z : 1, x : B \vdash \beta_0(z) e'' : A \). Now cut \( \Delta|\Gamma, z : 1 \vdash \alpha_0(z) e' : B \) into \( \Delta|\Gamma, z : 1, x : B \vdash \beta_0(z) e'' : A \) to get \( \Delta|\Gamma, z : 1 \vdash \beta_0(z) e''[\frac{e'}{x}] : A \). Now \( (\beta_0(z))[\frac{e'}{x}] \cong (\beta_0(z))[z] \), so we can apply \( 1_L \).

\[
\frac{\Delta|\Gamma, z : 1 \vdash \beta_0(z) e''[\frac{e'}{x}] : A}{\Delta|\Gamma, z : 1 \vdash \beta_0(z) \text{ let } * \text{ be } z \text{ in } e''[\frac{e'}{x}] : B}
\]

\( \otimes L \)

\[
\frac{\Delta|\Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash \alpha_0(z_1,z_2) e' : C}{\Delta|\Gamma, x : A \otimes B \vdash \alpha \text{ let } (x_1,x_2) \text{ be } x \text{ in } e' : C} \quad \frac{\Delta|\Gamma, x : A \otimes B, y : C \vdash \beta e : D}{\Delta|\Gamma, x : A \otimes B, y : C \vdash \beta \text{ let } \frac{y}{x} \text{ be } x \text{ in } e' : D}
\]

\( \otimes L \)

Now since we have \( x : A \otimes B \) in the derivation of \( \Delta|\Gamma, x : A \otimes B, y : C \vdash \beta e : D \), so by the inversion lemma we get \( \Delta|\Gamma, x : A \otimes B, x_1 : A, x_2 : B, y : C \vdash \beta_0(z_1,z_2) e'' : D \). Now cut \( \Delta|\Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash \alpha_0(z_1,z_2) e' : C \) into \( \Delta|\Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash \beta_0(z_1,z_2) e'' : D \) to get \( \Delta|\Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash \beta_0(z_1,z_2) e''[\frac{e'}{x}] : D \). Now \( (\beta_0(z_1,z_2))[\frac{e'}{x}] \cong (\beta_0(z_1,z_2))[\frac{y}{x}] \), so we can apply \( \otimes L \).

\[
\frac{\Delta|\Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash \beta_0(z_1,z_2) e''[\frac{e'}{x}] : D}{\Delta|\Gamma, x : A \otimes B \vdash \beta_0(z_1,z_2) \text{ let } (x_1,x_2) \text{ be } x \text{ in } e''[\frac{e'}{x}] : C}
\]

\( \rightarrow L \)
We cut $\Delta[\Gamma, f : A \rightarrow B, x : B \vdash \alpha_2 \; e' : C]$ into a weakened $\Delta[\Gamma, f : A \rightarrow B, y : C \vdash \beta e : D]$ and we get $\Delta[\Gamma, f : A \rightarrow B, x : B \vdash \beta[\frac{\alpha_2}{y}] e[\frac{e'}{x}] : D$. Now we have $(\beta[\frac{\alpha_2}{y}])[\frac{f[\alpha_1]}{x}] \cong (\beta[\frac{f[\alpha_1]}{y}])[\frac{\alpha_2}{f[\alpha_1]}] e[\frac{e'}{x}] \cong \beta[\frac{x}{y}]$ since $x \notin \beta$ and $\alpha \cong \alpha_2[\frac{f[\alpha_1]}{x}]$. So finally we can apply $\neg\sigma_L$ to get

$$\Delta[\Gamma, f : A \rightarrow B \vdash \alpha_2 t : A] \quad \Delta[\Gamma, f : A \rightarrow B, x : B \vdash \beta[\frac{\alpha_2}{y}] e[\frac{e'}{x}] : D] \quad \beta[\frac{x}{y}] \cong (\beta[\frac{[\alpha_1]}{x}])[\frac{f[\alpha_1]}{y}]$$

$$\Delta[\Gamma, f : A \rightarrow B \vdash \beta[\frac{\alpha_2}{y}] let x be f(t) in e[\frac{e'}{x}] : C] \quad \neg\sigma_L$$

$$\Theta_L$$

$\Delta[\Gamma, z : A \oplus B, x : A \vdash \alpha[\frac{z}{x}] e_1 : C] \quad \Delta[\Gamma, z : A \oplus B, y : B \vdash \alpha[\frac{z}{y}] e_2 : C]$

$$\Delta[\Gamma, z : A \oplus B \vdash case z of \text{inl}(x) \Rightarrow e_1, \text{inr}(y) \Rightarrow e_2 : C] \quad \Theta_L \quad \Delta[\Gamma, z : A \oplus B, w : C \vdash \beta e : D]$$

Now since we have $z : A \oplus B$ in the derivation of $\Delta[\Gamma, z : A \oplus B, w : C \vdash \beta e : D$, by the inversion lemma $e$ has a case in its body and can be rewritten as $e \cong \text{case } z \text{ of } \text{inl}(x) \Rightarrow e_1', \text{inr}(y) \Rightarrow e_2'$. Hence we know $\Delta[\Gamma, z : A \oplus B, x : A, w : C \vdash \alpha[\frac{z}{x}] e_1' : D]$, and $\Delta[\Gamma, z : A \oplus B, y : B, w : C \vdash \alpha[\frac{z}{y}] e_2' : D]$. Now cut $\Delta[\Gamma, z : A \oplus B, x : A \vdash \alpha[\frac{z}{x}] e_1 : C]$ into $\Delta[\Gamma, z : A \oplus B, x : A, w : C \vdash \alpha[\frac{z}{w}] e_2' : D]$. Now cut $\Delta[\Gamma, z : A \oplus B, x : A \vdash \alpha[\frac{z}{x}] e_1 : C]$ into $\Delta[\Gamma, z : A \oplus B, y : B, w : C \vdash \alpha[\frac{z}{w}] e_2' : D]$ to get $\Delta[\Gamma, z : A \oplus B, x : A \vdash (\beta[\frac{\alpha}{x}])[\alpha[\frac{z}{w}]] e_1'[\alpha[\frac{z}{w}]] : D]$. Furthermore cut $\Delta[\Gamma, z : A \oplus B, y : B \vdash \alpha[\frac{z}{y}] e_2 : C]$ into $\Delta[\Gamma, z : A \oplus B, y : B, w : C \vdash \alpha[\frac{z}{w}] e_2' : D]$ to get $\Delta[\Gamma, z : A \oplus B, y : B \vdash (\beta[\frac{\alpha}{y}])[\alpha[\frac{z}{w}]] e_2'[\alpha[\frac{z}{w}]] : D]$.
\[
\Delta|, z : A \oplus B, x : A \vdash_{(\beta[z])}(x) e'[x]_w : D \quad \Delta|, z : A \oplus B, y : B \vdash_{(\beta[z])}(y) e''[y]_w : D \\
\Delta|, z : A \oplus B \vdash_{\beta[z]} \text{case } z \text{ of } \mathtt{indl}(x) \Rightarrow e'[x]_w, \mathtt{inr}(y) \Rightarrow e''[y]_w : D \quad \oplus_L
\]

\&_{L_1}

\[
\Delta|, z : A \& B, x : A \vdash_{\alpha'} e' : C \quad \alpha \cong \alpha'[\frac{z}{w}]
\]

\[
\Delta|, z : A \& B \vdash_{\alpha} \text{let } <x, \_ > \text{ be } z \text{ in } e' : C \quad \Delta|, z : A \& B, w : C \vdash_{\beta} e : D
\]

\[
\Delta|, z : A \& B \vdash_{\beta[z]} e'[\text{let } <x, \_ > \text{ be } z \text{ in } e'] : D \quad \text{cut}
\]

We cut \(\Delta|, z : A \& B, x : A \vdash_{\alpha'} e' : C\) into a weakened \(\Delta|, z : A \& B, w : C \vdash_{\beta} e : D\) and we get \(\Delta|, z : A \& B, x : A \vdash_{(\beta[z])}(\frac{e'}{w}) : D\). Now we have \((\beta[\frac{\alpha'}{w}])[\frac{z}{x}] \cong (\beta[\frac{\alpha}{w}])[\frac{\alpha}{x}] \cong \beta[\frac{\alpha}{w}]\) since \(x \not\in \beta\) and \(\alpha \cong \alpha'[\frac{z}{w}]\). So finally we can apply \&_{L_1} to get

\[
\Delta|, z : A \& B, x : A \vdash_{\beta[z]} e'[\text{let } <x, \_ > \text{ be } z \text{ in } e'] : D \quad \beta[\frac{\alpha}{w}] \cong (\beta[\frac{\alpha'}{w}])[\frac{z}{x}] \quad \&_{L_1}
\]

\&_{L_2}

\[
\Delta|, z : A \& B, x : B \vdash_{\alpha'} e' : C \quad \alpha \cong \alpha'[\frac{z}{w}]
\]

\[
\Delta|, z : A \& B \vdash_{\alpha} \text{let } <\_ , x > \text{ be } z \text{ in } e' : C \quad \Delta|, z : A \& B, w : C \vdash_{\beta} e : D
\]

\[
\Delta|, z : A \& B \vdash_{\beta[z]} e'[\text{let } <\_ , x > \text{ be } z \text{ in } e'] : D \quad \text{cut}
\]

We cut \(\Delta|, z : A \& B, x : B \vdash_{\alpha'} e' : C\) into a weakened \(\Delta|, z : A \& B, w : C \vdash_{\beta} e : D\) and we get \(\Delta|, z : A \& B, x : B \vdash_{(\beta[z])}(\frac{e'}{w}) : D\). Now we have \((\beta[\frac{\alpha'}{w}])[\frac{z}{x}] \cong (\beta[\frac{\alpha}{w}])[\frac{\alpha'}{x}] \cong \beta[\frac{\alpha}{w}]\) since \(x \not\in \beta\) and \(\alpha \cong \alpha'[\frac{z}{w}]\). So finally we can apply \&_{L_2} to get

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\[\Delta \vdash \Gamma, z : A \& B, x : B \vdash \beta_{[\frac{\alpha}{\alpha^\prime}]} \ e_{[\frac{\alpha}{\alpha^\prime}]} : D \quad \beta_{[\frac{\alpha}{\alpha^\prime}]} \cong (\beta_{[\frac{\alpha}{\alpha^\prime}]})[\frac{z}{x}] \&_{L_1} \]

**MV**

\[\Delta, u \vdash \gamma : \Gamma_0 \quad \Delta, u \vdash e' : C \quad \delta_{\alpha_{[\frac{\alpha}{\alpha}]}[\frac{z}{x}]} \cong \alpha \quad \text{MV} \quad \Delta, u : [\Gamma_0]_{\alpha_{\alpha}} A \Gamma \vdash \beta_{[\frac{\alpha}{\alpha^\prime}]} e_{[\frac{\alpha}{\alpha^\prime}]} : D \]

We cut \(\Delta, u \vdash e' : C\) into a weakened \(\Delta, u : [\Gamma_0]_{\alpha_{\alpha}} A \Gamma \vdash \beta_{[\frac{\alpha}{\alpha^\prime}]} e_{[\frac{\alpha}{\alpha^\prime}]} : D\) and we get \(\Delta, u : [\Gamma_0]_{\alpha_{\alpha}} A \Gamma \vdash \beta_{[\frac{\alpha}{\alpha^\prime}]} e_{[\frac{\alpha}{\alpha^\prime}]} : D\). Now we have \((\beta_{[\frac{\alpha}{\alpha^\prime}]}[\frac{z}{x}]) \cong \beta_{[\frac{\alpha}{\alpha^\prime}][\frac{\alpha_{[\frac{\alpha}{\alpha}]}[\frac{z}{x}]}{x}]} \cong \beta_{[\frac{\alpha}{\alpha}]}\) since \(z \not\in \beta\) and \(\delta_{\alpha_{[\frac{\alpha}{\alpha}]}[\frac{z}{x}]} \cong \alpha\). So finally we can apply **MV** to get

\[\Delta, u \vdash \gamma : \Gamma_0 \quad \Delta, u : [\Gamma_0]_{\alpha_{\alpha}} A \Gamma \vdash \beta_{[\frac{\alpha}{\alpha}]} e_{[\frac{\alpha}{\alpha}]} : D \quad (\beta_{[\frac{\alpha}{\alpha}]}[\frac{\alpha_{[\frac{\alpha}{\alpha}]}[\frac{z}{x}]}{x}]) \cong \beta_{[\frac{\alpha}{\alpha}]} \quad \text{MV} \]

Hence we have completed our proof.

2. We write \(r\) for the derivation of \(A\) and \(s\) for the derivation of \(B\). We proceed by induction on \(s\).

Base cases:

1\(R\)

\[\Delta \vdash \Gamma_0 \vdash \alpha_0 e' : A \quad \Delta, u : [\Gamma_0]_{\alpha_{\alpha}} A \Gamma \vdash \ast : 1 \quad 1R\quad \text{cut!} \]

This is trivial since
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\[ \Delta \vdash \ast : \Gamma \quad 1_R \]

so we are done.

**id**

\[
\begin{align*}
\Delta \vdash \alpha \in \Gamma \\
\Delta, u : [\Gamma_0]_\alpha B \vdash x : A \\
\Delta \vdash x[e']_u : A
\end{align*}
\]

This is again trivial since

\[
\begin{align*}
x & : A \in \Gamma \\
\Delta & \vdash x : A \\
id
\end{align*}
\]

so we are done.

Inductive cases:

**1_L**

\[
\begin{align*}
\Delta, u & : [\Gamma_0]_\alpha B \vdash \Gamma, z : 1 \vdash t : A \\
\Delta, u & : [\Gamma_0]_\alpha B \vdash \Gamma, z : 1 \vdash \text{let } 1 \text{ be } z \text{ in } t : A \\
\Delta & \vdash \Gamma, z : 1 \vdash t[e']_u : A
\end{align*}
\]

Now we can cut \( \Delta \vdash \alpha \in \ast : B \) and \( \Delta, u : [\Gamma_0]_\alpha B \vdash \Gamma, z : 1 \vdash t[e']_u : A \) to get \( \Delta \vdash \Gamma, z : 1 \vdash t[e']_u : A \). Then by applying \( 1_L \) we get

\[
\begin{align*}
\Delta & \vdash \Gamma, z : 1 \vdash \text{let } 1 \text{ be } z \text{ in } t[e']_u : A
\end{align*}
\]
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\[ \langle \otimes R \rangle \]

\[
\Delta \vdash_{\alpha_0} e' : C \quad \Delta, u : [\Gamma_0]_{\alpha_0} C \mid \Gamma \vdash_{\alpha_1} e_1 : A \\
\Delta, u : [\Gamma_0]_{\alpha_0} C \mid \Gamma \vdash_{\alpha_2} e_2 : B \\
\text{cut!}\]

Now we can cut \( \Delta \mid \Gamma_0 \vdash_{\alpha_0} e' : C \) and \( \Delta, u : [\Gamma_0]_{\alpha_0} C \mid \Gamma \vdash_{\alpha_1} e_1 : A \) to get \( \Delta \mid \Gamma \vdash_{\alpha_1} e_1[\epsilon'_u] : A \), as well as \( \Delta \mid \Gamma_0 \vdash_{\alpha_0} e' : C \) and \( \Delta, u : [\Gamma_0]_{\alpha_0} C \mid \Gamma \vdash_{\alpha_2} e_2 : B \) to get \( \Delta \mid \Gamma \vdash_{\alpha_2} e_2[\epsilon'_u] : B \). Then by applying \( \otimes_R \) we get

\[
\Delta \mid \Gamma \vdash_{\alpha_1} e_1[\epsilon'_u] : A \quad \Delta \mid \Gamma \vdash_{\alpha_2} e_2[\epsilon'_u] : B \\
\alpha \simeq \alpha_1 \cup \alpha_2 \otimes_R \\
\langle \otimes L \rangle \]

\[
\Delta, u : [\Gamma_0]_{\alpha_0} D \mid \Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash_{\alpha_1[\epsilon_1, \epsilon_2]} e : C \\
\Delta, u : [\Gamma_0]_{\alpha_0} D \mid \Gamma, x : A \otimes B \vdash_{\alpha} \text{let } (x_1, x_2) \text{ be } x \text{ in } e : C \\
\text{cut!}
\]

Now we can cut \( \Delta \mid \Gamma_0 \vdash_{\alpha_0} e' : D \) and \( \Delta, u : [\Gamma_0]_{\alpha_0} D \mid \Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash_{\alpha_1[\epsilon_1, \epsilon_2]} e : C \) to get \( \Delta \mid \Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash_{\alpha_1[\epsilon_1, \epsilon_2]} e[\epsilon'_u] : C \). Then by applying \( \otimes_L \) we get

\[
\Delta \mid \Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash_{\alpha_1[\epsilon_1, \epsilon_2]} e[\epsilon'_u] : C \]

\[ \langle \circ R \rangle \]

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\[
\Delta, u : [\Gamma_0]_{\alpha_0} C | \Gamma, x : A \vdash_{\alpha_\text{ux}} t : B \qquad \Delta, u : [\Gamma_0]_{\alpha_0} C | \Gamma \vdash_\alpha \lambda x. t : A \nrightarrow B \quad \text{cut!}
\]

Now we can cut \(\Delta | \Gamma_0 \vdash_{\alpha_0} e' : C\) and \(\Delta, u : [\Gamma_0]_{\alpha_0} C | \Gamma, x : A \vdash_{\alpha_\text{ux}} t : B\) to get \(\Delta | \Gamma, x : A \vdash_{\alpha_\text{ux}} t[\frac{e'}{u}] : B\). Then by applying \(\nrightarrow R\) we get

\[
\Delta | \Gamma, x : A \vdash_{\alpha_\text{ux}} t[\frac{e'}{u}] : B \quad \text{cut!}
\]

Now we can cut \(\Delta | \Gamma_0 \vdash_{\alpha_0} e' : D\) and \(\Delta, u : [\Gamma_0]_{\alpha_0} D | \Gamma, f : A \nrightarrow B \vdash_{\alpha_1} t : A\) to get \(\Delta | \Gamma, f : A \nrightarrow B \vdash_{\alpha_1} t[\frac{e'}{u}] : A\), as well as \(\Delta | \Gamma_0 \vdash_{\alpha_0} e' : D\) and \(\Delta, u : [\Gamma_0]_{\alpha_0} D | \Gamma, f : A \nrightarrow B, x : B \vdash_{\alpha_2} e : C\) to get \(\Delta | \Gamma, f : A \nrightarrow B, x : B \vdash_{\alpha_2} e[\frac{e'}{u}] : C\).

Then by applying \(\nrightarrow L\) we get

\[
\Delta | \Gamma, f : A \nrightarrow B \vdash_{\alpha_1} t[\frac{e'}{u}] : A \quad \Delta | \Gamma, f : A \nrightarrow B, x : B \vdash_{\alpha_2} e[\frac{e'}{u}] : C \quad \Delta \vdash_\alpha \varepsilon \begin{pmatrix} e[\frac{e'}{u}] \end{pmatrix} \quad \text{cut!}
\]

As well as \(\Delta, u : [\Gamma_0]_{\alpha_0} C | \Gamma \vdash_\alpha \text{inl}(t) : A \noplus B \quad \oplus R_1\)
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Now we can cut $\Delta|\Gamma_0 \vdash_{\alpha_0} e' : C$ and $\Delta, u : [\Gamma_0|_{\alpha_0} \Gamma \vdash_{\alpha} t : A$ to get $\Delta|\Gamma \vdash_{\alpha} t^{[e']}_{[u]} : A$. Then by applying $\oplus_{R_1}$ we get

$$\Delta|\Gamma \vdash_{\alpha} inl(t^{[e']}_{[u]}) : A \oplus B$$

$\oplus_{R_2}$

$$\Delta|\Gamma \vdash_{\alpha} e' : C \quad \Delta, u : [\Gamma_0|_{\alpha_0} \Gamma \vdash_{\alpha} t : B$$

$$\Delta|\Gamma \vdash_{\alpha} inr(t^{[e']}_{[u]}) : A \oplus B$$

Now we can cut $\Delta|\Gamma_0 \vdash_{\alpha_0} e' : C$ and $\Delta, u : [\Gamma_0|_{\alpha_0} \Gamma \vdash_{\alpha} t : B$ to get $\Delta|\Gamma \vdash_{\alpha} t^{[e']}_{[u]} : B$. Then by applying $\oplus_{R_2}$ we get

$$\Delta|\Gamma \vdash_{\alpha} t^{[e']}_{[u]} : B$$

$\oplus_L$

$$\Delta|\Gamma \vdash_{\alpha} e' : D \quad \Delta, u : [\Gamma_0|_{\alpha_0} \Gamma \vdash_{\alpha} z : A \oplus B, x : A \vdash_{\alpha[\xi]} e_1 : C \quad \Delta, u : [\Gamma_0|_{\alpha_0} \Gamma \vdash_{\alpha} z : A \oplus B, y : B \vdash_{\alpha[\xi]} e_2 : C$$

$$\Delta|\Gamma, z : A \oplus B \vdash_{\alpha} \text{case } z \text{ of } inl(x) \Rightarrow e_1, inr(y) \Rightarrow e_2 : C$$

Now we can cut $\Delta|\Gamma_0 \vdash_{\alpha_0} e' : D$ and $\Delta, u : [\Gamma_0|_{\alpha_0} \Gamma \vdash_{\alpha} e_1^{[e']}_{[u]} : C$, as well as $\Delta|\Gamma_0 \vdash_{\alpha_0} e' : D$ and $\Delta, u : [\Gamma_0|_{\alpha_0} \Gamma \vdash_{\alpha} e_2^{[e']}_{[u]} : C$, to get $\Delta|\Gamma, z : A \oplus B, y : B \vdash_{\alpha[\xi]} e_1^{[e']}_{[u]} : C$. Then by applying $\oplus_L$ we get
Now we can cut $\Delta | \Gamma_0 \vdash \alpha_0 e' : C$ and $\Delta, u : [\Gamma_0]_{\alpha_0} C | \Gamma \vdash \alpha e_1 : A$ to get $\Delta | \Gamma \vdash \alpha e_1 [\frac{\epsilon_1}{\alpha}] : A$, as well as $\Delta | \Gamma_0 \vdash \alpha_0 e' : C$ and $\Delta, u : [\Gamma_0]_{\alpha_0} C | \Gamma \vdash \alpha_0 e_2 : B$ to get $\Delta | \Gamma \vdash \alpha_0 e_2 [\frac{\epsilon_2}{\alpha}] : B$. Then by applying $\&_R$ we get

$$
\Delta | \Gamma \vdash \alpha e_1 [\frac{\epsilon_1}{\alpha}] : A \quad \Delta | \Gamma \vdash \alpha e_2 [\frac{\epsilon_2}{\alpha}] : B
$$

$$
\Delta | \Gamma \vdash \alpha < e_1 [\frac{\epsilon_1}{\alpha}], e_2 [\frac{\epsilon_2}{\alpha}] > : A \& B
$$

Now we can cut $\Delta | \Gamma_0 \vdash \alpha_0 e' : D$ and $\Delta, u : [\Gamma_0]_{\alpha_0} D | \Gamma, z : A \& B, x : A \vdash \alpha' e : C \alpha \cong \alpha'[\frac{\epsilon}{\alpha}]$ to get $\Delta | \Gamma, z : A \& B, x : A \vdash \alpha' e [\frac{\epsilon}{\alpha}] : C$. Then by applying $\&_{L_1}$ we get

$$
\Delta | \Gamma, z : A \& B \vdash \alpha \text{ let } < x, > \text{ be } z \text{ in } e [\frac{\epsilon}{\alpha}] : C
$$

$$
\Delta | \Gamma, z : A \& B \vdash \alpha \text{ let } < x, > \text{ be } z \text{ in } e [\frac{\epsilon}{\alpha}] : C
$$
3. THE THEORY BEHIND JANET

\( \&_{L_2} \)

\[
\Delta, u : [\Gamma_0]_{\alpha_0}D | \Gamma, z : A \& B, x : B \vdash_{\alpha'} e : C \quad \alpha \equiv \alpha'[z]
\]

\[
\Delta \vdash \Gamma_0 \vdash_{\alpha_0} e' : D
\]

\[
\Delta, u : [\Gamma_0]_{\alpha_0}D | \Gamma, z : A \& B \vdash_{\alpha} e \quad \Delta, u : [\Gamma_0]_{\alpha_0}D | \Gamma, z : A \& B \vdash_{\alpha} \text{let } <_{\gamma}, x > \text{ be } z \text{ in } e : C
\]

\[
\Delta \vdash \Gamma, z : A \& B \vdash_{\alpha} e' : C
\]

Now we can cut \( \Delta | \Gamma_0 \vdash_{\alpha_0} e' : D \) and \( \Delta, u : [\Gamma_0]_{\alpha_0}D | \Gamma, z : A \& B, x : B \vdash_{\alpha'} e : C \) to get \( \Delta | \Gamma, z : A \& B, x : B \vdash_{\alpha'} e'[u] : C \). Then by applying \( \&_{L_2} \) we get

\[
\Delta | \Gamma, z : A \& B, x : B \vdash_{\alpha'} e'[u] : C \quad \alpha \equiv \alpha'[z]
\]

\( MV \)

We now have 2 different cases:

First we look at the case when \( u \) is the variable the MV rule is applied to:

\[
\Delta | \Gamma_0 \vdash_{\alpha_0} e' : A \quad \Delta, u | \Gamma, z : A \vdash_{\beta} e : C
\]

\[
\Delta, u : [\Gamma_0]_{\alpha_0}A | \Gamma \vdash z \text{ be } u[\theta] \text{ in } e : C \quad \beta[\alpha_0[z]] \equiv \alpha
\]

\[
\Delta | \Gamma \vdash \alpha \text{ let } u[\theta] \text{ in } e : C
\]

Now we can cut \( \Delta | \Gamma_0 \vdash_{\alpha_0} e' : A \) and \( \Delta, u | \Gamma, z : A \vdash_{\beta} e : C \) to get \( \Delta | \Gamma, z : A \vdash_{\beta} e'[u] : C \), as well as cutting \( \Delta | \Gamma_0 \vdash_{\alpha_0} e' : A \) into \( \Delta, u | \Gamma \vdash_{\gamma} \theta : \Gamma_0 \) to get \( \Delta | \Gamma \vdash_{\gamma} \theta[z] : \Gamma_0 \). Now composing this with \( \Delta | \Gamma_0 \vdash_{\alpha_0} e' : A \) we get \( \Delta | \Gamma \vdash_{\alpha_0[\gamma]} e'[u] : A \).

Then by applying cut we get

\[
\Delta | \Gamma \vdash_{\beta[\alpha_0[z]]} (e'[u])[\theta[z]] : C
\]
Now since $\beta[\alpha_0[z]] \simeq \alpha$, we are done.

The second case is when the $MV$ rule is not applied to $u$:

$$\Delta, v : [\Gamma_0]_\alpha A | \Gamma_1 \vdash \alpha_1 e' : B \quad \Delta, u, v | \Gamma, z : A \vdash_\beta e : C \quad \frac{\beta[\alpha_0[z]] \simeq \alpha}{MV} \quad \Delta, u : [\Gamma_1]_\alpha B, v : [\Gamma_0]_\alpha A | \Gamma_1 \vdash \alpha_0 \text{ let } z \text{ be } v[\theta] \text{ in } e : C \quad \text{cut!}$$

Now we can cut $\Delta, v : [\Gamma_0]_\alpha A | \Gamma_1 \vdash \alpha_1 e' : B$ into $\Delta, u, v | \Gamma, \theta : \Gamma_0$ to get $\Delta, v | \Gamma, \theta[\theta'[u]] : \Gamma_0$. Then we cut $\Delta, v : [\Gamma_0]_\alpha A | \Gamma_1 \vdash \alpha_1 e' : B$ into $\Delta, u, v | \Gamma, z : A \vdash_\beta e : C$ to get $\Delta, v | \Gamma, z : A \vdash_\beta e[e'[u]] : C$. Now we reapply $MV$ to get

$$\Delta, v | \Gamma, \theta[\theta'[u]] : \Gamma_0 \quad \Delta, v | \Gamma, z : A \vdash_\beta e[e'[u]] : C \quad \frac{\beta[\alpha_0[z]] \simeq \alpha}{MV} \quad \Delta, v : [\Gamma_0]_\alpha A | \Gamma_1 \vdash \alpha \text{ let } z \text{ be } v[\theta[u]] \text{ in } e[e'[u]] : C$$

$\Box$
4. AN IMPLEMENTATION SEQUENT CALCULUS

4. An Implementation Sequent Calculus

In order to implement our proof assistant, we had to translate the base sequent calculus from Figure 13 to rules that we can easily implement. The main challenge is representing the $\alpha$s and the equations they are abiding. We introduce resource variables ($a_1, a_2, ...$) to stand for $(\alpha_1, \alpha_2, ...)$ and a restriction context $\mathcal{X}$ which keeps track of all of the restrictions that will help us determine appropriate $\alpha$s. The rules of this new sequent calculus are mirroring the rules from the base sequent calculus, except that each sequent now also contains a $\mathcal{X}$ context.

The restrictions take one of the following 6 forms:

1. $a = \{x_1, x_2, ..., x_n\}$ which tells us that $\alpha$ must contain exactly the variables $\{x_1, x_2, ..., x_n\}$.
2. $a = a_1 \cup a_2$ which tells us that $\alpha \cong \alpha_1 \cup \alpha_2$.
3. $a[\frac{x}{y}] = a'$ which tells us that $\alpha[\frac{x}{y}] \cong \alpha'$.
4. $a = a'[\frac{x}{y}]$ which tells us that $\alpha \cong \alpha'[\frac{x}{y}]$.
5. $a = a_2[\frac{f \cup \alpha_1}{x}]$ which tells us that $\alpha \cong \alpha_2[\frac{f \cup \alpha_1}{x}]$.
6. $a = a'[\frac{\alpha_0[n]}{z}]$ which tells us that $\alpha \cong \alpha'[\frac{\alpha_0[n]}{z}]$.

We say that $\mathcal{X} \models \frac{\alpha_1}{a_1}, \frac{\alpha_2}{a_2}, ..., \frac{\alpha_n}{a_n}$, or $\mathcal{X}$ is consistent, if there are $\alpha_1, ..., \alpha_n$ for which the restrictions in $\mathcal{X}$ hold. Note that this does not uniquely identify the $\alpha$’s since in some cases (like splitting an $\alpha$ during a tensor right rule and then only having metavariables as terms on both sides), the $\alpha$’s have many different values for which all restrictions hold.

In order to be able to tell which rules can be applied to which variables under every $a$ during the process of building the proof, we can compute the upper bound
multiset of variables each \( a \) can use by solving all of the restrictions in \( \mathcal{X} \). We use the following notation: \( a \subset_{\mathcal{X}} \{x_1, ..., x_n\} \) to say that by solving the restrictions in \( \mathcal{X} \) we can generate the upper bound \( x_1, ..., x_n \). In the implementation we cache these results and just update them by subtracting variables as they are being used in other branches of the proof. In Section 4.1 we prove a theorem that from a derivation of a term in the sequent calculus from Figure 14, we can produce a derivation of a term of the same type in the sequent calculus from Figure 13.

4.1. From an implementation calculus proof to a base calculus proof.

We want to prove that if we have a consistent set of constraints \( \mathcal{X} \) and a proof of a theorem in our implementation calculus, then we can construct a proof of the same theorem in our base calculus as well.

**Theorem:**

If \( \mathcal{X} \models \frac{\alpha_1}{a_1}, ..., \frac{\alpha_n}{a_n} \) and \( \mathcal{X} \models u_0 : [\Gamma_0]_{a_0} A_0, ..., u_k : [\Gamma_k]_{a_k} A_k | \Gamma \vdash_{\alpha_i} A \),

then \( u_0 : [\Gamma_0]_{a_0} A_0, ..., u_k : [\Gamma_k]_{a_k} A_k | \Gamma \vdash_{\alpha_i} A \).

**Proof.**

Base cases:

\[ 1_R \]

\[
\frac{(a = \{\}) \in \mathcal{X}}{\mathcal{X} \models \Delta | \Gamma \vdash_{\alpha} \star : 1_R}
\]

Now since \( (a = \{\}) \in \mathcal{X} \), and \( \mathcal{X} \models \frac{\alpha}{a} \), \( \alpha \cong \). Therefore,
\( \Gamma ::= \cdot \mid x : A \mid \Gamma_1 \cup \Gamma_2 \)

\( \Delta ::= \cdot \mid u : [\Gamma_0]_{a_0} A \mid \Delta_1 \cup \Delta_2 \)

\( \gamma ::= \cdot \mid \gamma, \frac{a}{y_i} \)

\( \mathcal{X} ::= \cdot \mid \mathcal{X}, \ a = \{x_1, x_2, \ldots, x_n\} \mid \mathcal{X}, \ a = a_1 \cup a_2 \mid \mathcal{X}, \ a = a'[\frac{e}{y}] \mid \mathcal{X}, \ a = a'[\frac{a_0}{x}] \)

\( (a = \{\}) \in \mathcal{X} \frac{\mathcal{X}|\Delta|\Gamma \vdash_a x : 1}{\mathcal{X}|\Delta|\Gamma \vdash_a x : 1 \ R} \)

\( \frac{\mathcal{X}|\Delta|\Gamma \vdash_a e_1 : A \quad \mathcal{X}|\Delta|\Gamma \vdash_a e_2 : B \quad a = a_1 \cup a_2 \in \mathcal{X}}{\mathcal{X}|\Delta|\Gamma \vdash_a (e_1, e_2) : A \otimes B} \quad \otimes_R \)

\( \frac{\mathcal{X}|\Delta|\Gamma \vdash_a e : A \otimes B, x_1 : A, x_2 : B \vdash \ e : C \quad a \in \mathcal{X}}{\mathcal{X}|\Delta|\Gamma \vdash_a \ (x_1, x_2) \in \mathcal{X}} \quad \otimes_L \)

\( \frac{\mathcal{X}|\Delta|\Gamma \vdash_a e : A \otimes B \quad a \in \mathcal{X}}{\mathcal{X}|\Delta|\Gamma \vdash_a \lambda x.t : A \rightarrow B} \quad \rightarrow_R \)

\( \frac{\mathcal{X}|\Delta|\Gamma \vdash_a e : A \otimes B \quad a \in \mathcal{X}}{\mathcal{X}|\Delta|\Gamma \vdash_a inl(t) : A \otimes B} \quad \otimes_{R_1} \)

\( \frac{\mathcal{X}|\Delta|\Gamma \vdash_a e : A \otimes B \quad a \in \mathcal{X}}{\mathcal{X}|\Delta|\Gamma \vdash_a inr(t) : A \otimes B} \quad \otimes_{R_2} \)

\( \frac{\mathcal{X}|\Delta|\Gamma \vdash_a e_1 : C \quad \mathcal{X}|\Delta|\Gamma, z, y : B \vdash a_2 \ e_2 : C \quad a \in \mathcal{X}}{\mathcal{X}|\Delta|\Gamma \vdash_a (e_1, \ e_2) : C} \quad \oplus_L \)

\( \frac{\mathcal{X}|\Delta|\Gamma \vdash_a e_1 : A \quad \mathcal{X}|\Delta|\Gamma \vdash_a e_2 : B \quad a \in \mathcal{X}}{\mathcal{X}|\Delta|\Gamma \vdash_a \ e_1, e_2 : A \wedge B} \quad \wedge_R \)

\( \frac{\mathcal{X}|\Delta|\Gamma \vdash_a e : A \wedge B, x : A \vdash \ e : C \quad a \in \mathcal{X}}{\mathcal{X}|\Delta|\Gamma \vdash_a < x, e > \in \mathcal{X}} \quad \&_{L_1} \)

\( \frac{\mathcal{X}|\Delta|\Gamma \vdash_a e : A \wedge B, x : B \vdash \ e : C \quad a \in \mathcal{X}}{\mathcal{X}|\Delta|\Gamma \vdash_a < x, e > \in \mathcal{X}} \quad \&_{L_2} \)

\( \frac{\mathcal{X}|\Delta, u : [\Gamma_0]_{a_0} A \vdash z \in \mathcal{X}}{\mathcal{X}|\Delta, u : [\Gamma_0]_{a_0} A \vdash z \in \mathcal{X}} \quad \text{MV} \)

**Figure 14.** Implementation Sequent Calculus
4. AN IMPLEMENTATION SEQUENT CALCULUS

\[
\Delta|\Gamma \vdash \alpha \ast : 1 \quad 1_R
\]

**id**

\[
x : A \in \Gamma \quad (a = \{x\}) \in \mathcal{X}
\]

\[
\mathcal{X}|\Delta|\Gamma \vdash x : A \quad \text{id}
\]

Now since \((a = \{x\}) \in \mathcal{X}\), and \(\mathcal{X} \models \frac{a}{a}, \alpha \equiv x\). Therefore,

\[
x : A \in \Gamma \quad (a = \{x\}) \in \mathcal{X}\]

\[
\Delta|\Gamma \vdash \alpha \ast : 1 \quad \text{id}
\]

Inductive cases:

**1L**

\[
\mathcal{X}|\Delta|\Gamma, z : 1 \vdash a' t : A \quad a[\{z\}] = a' \in \mathcal{X}
\]

\[
\mathcal{X}|\Delta|\Gamma, z : 1 \vdash \text{let } z \text{ be } a' \text{ in } t : A \quad 1_L
\]

Now by applying IH to \(\mathcal{X}|\Delta|\Gamma, z : 1 \vdash a' t : A\) we get \(\Delta|\Gamma, z : 1 \vdash a' t : A\). Now since \(a[\{z\}] = a' \in \mathcal{X}\), and \(\mathcal{X} \models \frac{a}{a}, \alpha' \equiv \alpha\), so by applying 1L we get

\[
\Delta|\Gamma, z : 1 \vdash a[z] t : A
\]

\[
\Delta|\Gamma, z : 1 \vdash \text{let } z \text{ be } a' \text{ in } t : A \quad 1_L
\]

**⊗R**

\[
\mathcal{X}|\Delta|\Gamma \vdash a_1 e_1 : A \quad \mathcal{X}|\Delta|\Gamma \vdash a_2 e_2 : B \quad a = a_1 \cup a_2 \in \mathcal{X}
\]

\[
\mathcal{X}|\Delta|\Gamma \vdash (e_1, e_2) : A \otimes B \quad \otimes_R
\]
Now by applying IH to $\mathcal{X}\vDash \Delta|\Gamma \vdash a_1, e_1 : A$ and $\mathcal{X}\vDash \Delta|\Gamma \vdash a_2, e_2 : B$ we get $\Delta|\Gamma \vdash a_1, e_1 : A$ and $\Delta|\Gamma \vdash a_2, e_2 : B$. Now since $\mathcal{X} \models a \leftrightarrow a_1 \cup a_2$, and $a = a_1 \cup a_2 \in \mathcal{X}$, we have $\alpha \models a_1 \cup a_2$. Then we can apply $\otimes_R$ again to get

$$
\frac{\Delta|\Gamma \vdash a_1, e_1 : A \quad \Delta|\Gamma \vdash a_2, e_2 : B \quad \alpha \models a_1 \cup a_2}{\Delta|\Gamma \vdash (e_1, e_2) : A \otimes B} \otimes_R
$$

$$
\otimes_L
$$

$$
\mathcal{X}\vDash \Delta|\Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash a' e : C \quad a[x_1, x_2] = a' \in \mathcal{X}
$$

By applying the IH to $\mathcal{X}\vDash \Delta|\Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash a' e : C$ we get $\Delta|\Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash a' e : C$. Now since $\mathcal{X} \models a \leftrightarrow a'$ and $a[x_1, x_2] = a' \in \mathcal{X}$, we have $\alpha[x_1, x_2] \models a'$. Now we can reapply $\otimes_L$ to get

$$
\frac{\Delta|\Gamma, x : A \otimes B, x_1 : A, x_2 : B \vdash a'[x_1, x_2] e : C}{\Delta|\Gamma, x : A \otimes B \vdash (x_1, x_2) \text{ be } x \text{ in } e : C} \otimes_L
$$

$$
\neg o_R
$$

$$
\mathcal{X}\vDash \Delta|\Gamma, x : A \vdash a' t : B \quad a[x] = a' \in \mathcal{X}
$$

By applying the IH to $\mathcal{X}\vDash \Delta|\Gamma, x : A \vdash a' t : B$ we get $\Delta|\Gamma, x : A \vdash a' t : B$. Now since $\mathcal{X} \models a \leftrightarrow a'$ and $a[x] = a' \in \mathcal{X}$, we have $\alpha \cup x \models a'$. Now we can reapply $\neg o_R$ to get

$$
\frac{\Delta|\Gamma, x : A \vdash a \cup x t : B}{\Delta|\Gamma \vdash \lambda x t : A \rightarrow B} \neg o_R
$$
4. AN IMPLEMENTATION SEQUENT CALCULUS

\[ \vdash_{L} \]

\[ \Delta|\Gamma, f : A \rightarrow B \vdash a \rightarrow t : A \quad \Delta|\Gamma, f : A \rightarrow B, x : B \rightarrow\alpha_2 e : C \quad \alpha \equiv a_2[f/x] \in \mathcal{X} \]

\[ \vdash_{L} \]

By applying the IH to \( \Delta|\Gamma, f : A \rightarrow B \vdash a \rightarrow t : A \) and \( \Delta|\Gamma, f : A \rightarrow B, x : B \rightarrow\alpha_2 e : C \), we get \( \Delta|\Gamma, f : A \rightarrow B \vdash a \rightarrow t : A \) and \( \Delta|\Gamma, f : A \rightarrow B, x : B \rightarrow\alpha_2 e : C \).

Now since \( \mathcal{X} \vdash a \rightarrow\alpha_1, \alpha_2 \rightarrow\alpha_2 \), and \( a \rightarrow a_2[f/x] \in \mathcal{X} \), we have \( \alpha \equiv a_2[f/x] \). Then we can apply \( \vdash_{L} \) again to get

\[ \Delta|\Gamma, f : A \rightarrow B \vdash \alpha \rightarrow t : A \quad \Delta|\Gamma, f : A \rightarrow B, x : B \rightarrow\alpha_2 e : C \quad \alpha \equiv a_2[f/x] \]

\[ \vdash_{L} \]

\( \Theta R_1 \)

\[ \mathcal{X}|\Delta|\Gamma \vdash a \rightarrow t : A \quad a[f] = a' \in \mathcal{X} \]

\[ \mathcal{X}|\Delta|\Gamma \vdash inl(t) : A \oplus B \quad \Theta R_1 \]

By applying IH to \( \mathcal{X}|\Delta|\Gamma \vdash a \rightarrow t : A \) we get \( \Delta|\Gamma \vdash a' \rightarrow t : A \). Now since \( \mathcal{X} \vdash a, a' \rightarrow a' \) and \( a[f] = a' \in \mathcal{X} \), we have \( \alpha \equiv a' \). Now we can reapply \( \Theta R_1 \) to get

\[ \Delta|\Gamma \vdash a \rightarrow t : A \]

\[ \Delta|\Gamma \vdash inl(t) : A \oplus B \quad \Theta R_1 \]

\( \Theta R_2 \)

\[ \mathcal{X}|\Delta|\Gamma \vdash a \rightarrow t : B \quad a[f] = a' \in \mathcal{X} \]

\[ \mathcal{X}|\Delta|\Gamma \vdash inr(t) : A \oplus B \quad \Theta R_2 \]
By applying IH to $\mathcal{X}|\Delta|\Gamma \vdash_{\alpha'} t : B$ we get $\Delta|\Gamma \vdash_{\alpha} t : B$. Now since $\mathcal{X} \models \frac{a}{a'}$ and $a|\{1\}] = a' \in \mathcal{X}$, we have $\alpha \cong \alpha'$. Now we can reapply $\oplus_{R_2}$ to get

\[
\Delta|\Gamma \vdash_{\alpha} t : B
\]

\[
\Delta|\Gamma \vdash_{\alpha} inr(t) : A \oplus B \quad \oplus_{L}
\]

By applying IH to $\mathcal{X}|\Delta|\Gamma, z, x : A \vdash_{a_1} e_1 : C$ and $\mathcal{X}|\Delta|\Gamma, z, y : B \vdash_{a_2} e_2 : C$ we get $\Delta|\Gamma, z, x : A \vdash_{a_1} e_1 : C$ and $\Delta|\Gamma, z, y : B \vdash_{a_2} e_2 : C$. Now since $\mathcal{X} \models \frac{a}{a_1}, \frac{a_2}{a_1}$, and $a|\{\frac{x}{z}\}] = a_1 \in \mathcal{X}$ and $a|\{\frac{y}{z}\}] = a_2 \in \mathcal{X}$, we get $\alpha|\{\frac{x}{z}\}] \cong a_1$ and $\alpha|\{\frac{y}{z}\}] \cong a_2$. Now we can reapply $\oplus_{L}$ to get

\[
\Delta|\Gamma, z, x : A \oplus B \vdash_{\alpha} \text{case } z \text{ of } \text{inl}(x) \Rightarrow e_1, \text{inr}(y) \Rightarrow e_2 : C
\]

\[
\Delta|\Gamma, z, x : A \oplus B \vdash_{\alpha} \text{case } z \text{ of } \text{inl}(x) \Rightarrow e_1, \text{inr}(y) \Rightarrow e_2 : C \quad \oplus_{L}
\]

By applying IH to $\mathcal{X}|\Delta|\Gamma \vdash_{\alpha_2} e_2 : B$ we get $\Delta|\Gamma \vdash_{\alpha_1} e_1 : A$ and $\Delta|\Gamma \vdash_{\alpha_2} e_2 : B$. Now since $\mathcal{X} \models \frac{a}{a_1}, \frac{a_2}{a_1}$, and $a|\{\frac{1}{1}\}] = a_1 \in \mathcal{X}$ and $a|\{\frac{1}{1}\}] = a_2 \in \mathcal{X}$, we get $\alpha \cong \alpha_1$ and $\alpha \cong \alpha_2$. Now we can reapply $\&_R$ to get

\[
\Delta|\Gamma \vdash_{\alpha_1} e_1 : A \quad \Delta|\Gamma \vdash_{\alpha_2} e_2 : B \quad a|\{\frac{1}{1}\}] = a_1 \in \mathcal{X} \quad a|\{\frac{1}{1}\}] = a_2 \in \mathcal{X}
\]

\[
\mathcal{X}|\Delta|\Gamma \vdash_{a} e_1, e_2 : A \& B \quad \&_R
\]

4. AN IMPLEMENTATION SEQUENT CALCULUS
4. AN IMPLEMENTATION SEQUENT CALCULUS

&_{L_1}

\[ \frac{\mathcal{X}\mid \Delta\mid \Gamma, z : A \& B, z : A \vdash \alpha, e : C \quad \alpha', \theta : \Gamma_0}{\mathcal{X}\mid \Delta\mid \Gamma, z : A \& B \vdash \alpha' \mid \mathcal{X}} \]

By applying IH to \( \mathcal{X}\mid \Delta\mid \Gamma, z : A \& B, x : A \vdash \alpha, e : C \) we get \( \Delta\mid \Gamma, z : A \& B, x : A \vdash \alpha' \mid \mathcal{X} \). Now since \( \mathcal{X} \vdash \alpha, \alpha' \) and \( a = \alpha' \mid \{x\} \in \mathcal{X} \), we have \( \alpha \cong \alpha' \mid \{z\} \). Now we can reapply \&_{L_2} to get

&_{L_2}

\[ \frac{\mathcal{X}\mid \Delta\mid \Gamma, z : A \& B, x : A \vdash \alpha, e : C \quad \alpha', \theta : \Gamma_0}{\mathcal{X}\mid \Delta\mid \Gamma, z : A \& B \vdash \alpha' \mid \mathcal{X}} \]

By applying IH to \( \mathcal{X}\mid \Delta\mid \Gamma, z : A \& B, x : B \vdash \alpha, e : C \) we get \( \Delta\mid \Gamma, z : A \& B, x : B \vdash \alpha' \mid \mathcal{X} \). Now since \( \mathcal{X} \vdash \alpha, \alpha' \) and \( a = \alpha' \mid \{x\} \in \mathcal{X} \), we have \( \alpha \cong \alpha' \mid \{z\} \). Now we can reapply \&_{L_2} to get

\[ \frac{\mathcal{X}\mid \Delta, z : A \& B, x : B \vdash \alpha, e : C \quad \alpha, \theta : \Gamma_0}{\mathcal{X}\mid \Delta, z : A \& B \vdash \alpha \mid \mathcal{X}} \]

\[ \frac{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0}{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0} \]

\[ \frac{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0}{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0} \]

\[ \frac{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0}{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0} \]

\[ \frac{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0}{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0} \]

\[ \frac{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0}{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0} \]

\[ \frac{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0}{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0} \]

\[ \frac{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0}{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0} \]

\[ \frac{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0}{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0} \]

\[ \frac{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0}{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0} \]

\[ \frac{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0}{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0} \]

\[ \frac{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0}{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0} \]

\[ \frac{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0}{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0} \]

\[ \frac{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0}{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0} \]

\[ \frac{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0}{\mathcal{X}\mid \Delta, u : [\Gamma_0]_u A \vdash \theta : \Gamma_0} \]
By applying IH to $\mathcal{X}|\Delta, u : [\Gamma_0|_{a_0} A]|\Gamma, z : A \vdash_{a'} e : C$ and $\mathcal{X}|\Delta, u : [\Gamma_0|_{a_0} A]|\Gamma \vdash_{\theta} \theta : \Gamma_0$ we get $\Delta, u : [\Gamma_0|_{a_0} A]|\Gamma, z : A \vdash_{a'} e : C$ and $\Delta, u : [\Gamma_0|_{a_0} A]|\Gamma \vdash_{\theta} \theta : \Gamma_0$. Now since $\mathcal{X} \models \frac{\alpha}{a}, \frac{\alpha'}{a'} \frac{a_0}{a_0}$ and $a = a'[\frac{a_0[z]}{z}] \in \mathcal{X}$, we have $\alpha \equiv \alpha'[\frac{a_0[z]}{z}]$. Now we can reapply $MV$ to get

$$\Delta, u : [\Gamma_0|_{a_0} A]|\Gamma \vdash_{\alpha} \theta : \Gamma_0 \quad \Delta, u : [\Gamma_0|_{a_0} A]|\Gamma, z : A \vdash_{a'} e : C \quad \alpha \equiv \alpha'[\frac{a_0[z]}{z}]$$

$$\Delta, u : [\Gamma_0|_{a_0} A]|\Gamma \vdash_{\alpha} \text{let } z \text{ be } u[\theta] \text{ in } e : C$$

$MV$

4.2. Validity preservation.

We want to show that at every step of our term building process we have a term that typechecks and whose restriction context is consistent, so therefore by the theorem in Section 4.1, it has a proof in our base logical sequent calculus too.

We first show that we always start with a term that typechecks and has a consistent starting restriction context. Since we only construct a term made of a single metavariable whose context is the whole context entered so far, and whose restrictions are true for $\alpha \equiv \Gamma$ and $\alpha' \equiv z$, the proof is the following:

First let $M = \Gamma \vdash_{id} \text{id} : \Gamma$ and $a = a'[\frac{a[\text{id}]}{z}]u : [\Gamma]_a A|\Gamma, z : A \vdash_{a'} z : A$.

So we have

$$\Gamma \vdash_{id} \text{id} : \Gamma \quad M \quad a = a'[\frac{a[\text{id}]}{z}] \in a' = \{z\}, a = \Gamma, a = a'[\frac{a[\text{id}]}{z}] \quad MV$$

Lemma 1 ($\Delta$ weakening):

If $\mathcal{X}|\Delta|\Gamma \vdash_a A$ then $\mathcal{X}|\Delta, u : [\Gamma_0|_{a_0} A]|\Gamma \vdash_a A$, where $a_0$ is a fresh resource variable.
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Proof. By induction on $\mathcal{X}|\Delta|\Gamma \vdash a \ A$. □

Lemma 2 ($\mathcal{X}$ weakening):
If $\mathcal{X}|\Delta|\Gamma \vdash a \ A$, then $\mathcal{X}, \mathcal{X}'|\Delta|\Gamma \vdash a \ A$.

Proof. By induction on $\mathcal{X}|\Delta|\Gamma \vdash a \ A$. □

Cut! rule for the $\mathcal{X}$ calculus:
If $\mathcal{X}|\Delta, u : [\Gamma_0]_a A_0|\Gamma \vdash e : A$, and $\mathcal{X}|\Delta|\Gamma_0 \vdash a_0 \ A_0$, then $\mathcal{X}|\Delta|\Gamma \vdash a \ A$.

Proof. By induction that follows the same structure as the cut! proof in Section 3.3. □

Corollary:
If $\mathcal{X}|\Delta, u : [\Gamma_0]_a A_0|\Gamma \vdash e : A$ and $e$ contains let $z$ be $u[\theta]$ in $z$ in it, and we have $\mathcal{X}, \mathcal{X}'|\Delta, \Delta'|\Gamma_0 \vdash a_0 \ t : A_0$, then $\mathcal{X}, \mathcal{X}'|\Delta, \Delta'|\Gamma \vdash e[t \ \mathsf{let} \ z \ \mathsf{be} \ u[\theta] \ \mathsf{in} \ z] : A$.

Proof.
We apply Lemma 1 multiple times to $\mathcal{X}|\Delta, u : [\Gamma_0]_a A_0|\Gamma \vdash e : A$, to get $\mathcal{X}|\Delta, u : [\Gamma_0]_a A_0, \Delta'|\Gamma \vdash a_0 \ e : A$. We then apply Lemma 2 to get $\mathcal{X}, \mathcal{X}'|\Delta, u : [\Gamma_0]_a A_0, \Delta'|\Gamma \vdash a_0 \ t : A_0$. Now we just Cut! $\mathcal{X}, \mathcal{X}'|\Delta, \Delta'|\Gamma_0 \vdash a_0 \ t : A_0$ into this to get $\mathcal{X}, \mathcal{X}'|\Delta, \Delta'|\Gamma \vdash e[t \ \mathsf{let} \ z \ \mathsf{be} \ u[\theta] \ \mathsf{in} \ z] : A$. □

Definition:
A goal refinement is the process of taking a proof $\mathcal{X}|\Delta, u : [\Gamma_0]_a A_0|\Gamma \vdash e : A$ and constructing $\mathcal{X}, \mathcal{X}'|\Delta, \Delta'|\Gamma \vdash a_0 \ e[t \ \mathsf{let} \ z \ \mathsf{be} \ u[\theta] \ \mathsf{in} \ z] : A$ by building a term $t$ such that $\mathcal{X}, \mathcal{X}'|\Delta, \Delta'|\Gamma_0 \vdash a_0 \ t : A_0$ (obtained by applying one of 14 refinement rules) and then substituting this term $t$ for $u$ in $e$. The rules available are dependent on the current state of the sequent and are presented below (the notation $a_0 = \{x_1, ..., x_n\} \not\subset X$ means that $a_0$ is not already set to something by $X$):

1. $\mathsf{id}(x)$ - available when $x : A_0 \in \Gamma_0, a_0 \subset \mathcal{X} \ {x, \ldots}$, and $a_0 = \{x_1, \ldots, x_n\} \not\subset \mathcal{X}$. 

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2. $1_R$ - available when $A_0 = 1$ and $a_0 = \{x_1, ..., x_n\} \not\subseteq \mathcal{X}$.
3. $1_L(z)$ - available when $z : 1 \in \Gamma_0$, $a_0 \subseteq_X \{z, \ldots\}$, and $a_0 = \{x_1, ..., x_n\} \not\subseteq \mathcal{X}$.
4. $\otimes_R$ - available when $A_0 = B \otimes C$.
5. $\otimes_L(x)$ - available when $x : B \otimes C \in \Gamma_0$, $a_0 \subseteq_X \{x, \ldots\}$ and $a_0 = \{x_1, ..., x_n\} \not\subseteq \mathcal{X}$.
6. $\rightarrow_R$ - available when $A_0 = B \rightarrow C$.
7. $\rightarrow_L(f)$ - available when $f : B \rightarrow C \in \Gamma_0$, $a_0 \subseteq_X \{f, \ldots\}$ and $a_0 = \{x_1, ..., x_n\} \not\subseteq \mathcal{X}$.
8. $\oplus_{R_1}$ - available when $A_0 = B \oplus C$.
9. $\oplus_{R_2}$ - available when $A_0 = B \oplus C$.
10. $\oplus_L(z)$ - available when $z : B \oplus C \in \Gamma_0$, $a_0 \subseteq_X \{z, \ldots\}$ and $a_0 = \{x_1, ..., x_n\} \not\subseteq \mathcal{X}$.
11. $\&_R$ - available when $A_0 = B \& C$.
12. $\&_{L_1}(z)$ - available when $z : B \& C \in \Gamma_0$, $a_0 \subseteq_X \{z, \ldots\}$ and $a_0 = \{x_1, ..., x_n\} \not\subseteq \mathcal{X}$.
13. $\&_{L_2}(z)$ - available when $z : B \& C \in \Gamma_0$, $a_0 \subseteq_X \{z, \ldots\}$ and $a_0 = \{x_1, ..., x_n\} \not\subseteq \mathcal{X}$.
14. $MV(v)$ - available when $v \in \Delta$.

**Theorem:**

Every goal refinement in a term that typechecks under a consistent restriction context, results in a term that also typechecks under a consistent restriction context.

**Proof.**

We are given $\mathcal{X}|\Delta, u : [\Gamma_0]_{a_0} A_0 \vdash e : A$ and we know that $\mathcal{X}$ is consistent. We want to refine the goal $u$, so we first create $\mathcal{X}, \mathcal{X}'|\Delta, \mathcal{X}'|\Gamma_0 \vdash t : A_0$. We proceed by a proof of reasoning by cases on the type of rules used to refine the goal. We
present the \( id, \otimes_R \) and \( \otimes_L \) rules.

\textbf{id}

The proof assistant only allows us to apply an id-rule on a variable \( x \) if \( a_0 \) has not already been set to something else inside of \( \mathcal{X} \), and if \( x \) is contained in the upper bound multiset of variables that \( a_0 \) can use. In that case we get:

\[
\frac{x : A_0 \in \Gamma_0 \quad (a_0 = \{x\}) \in \mathcal{X}, (a_0 = \{x\})}{\mathcal{X}, (a_0 = \{x\})|\Delta| \Gamma_0 \vdash_a x : A_0} \quad \text{id}
\]

Since \( a_0 = \{x_1, \ldots, x_n\} \not\in \mathcal{X} \), and \( x \) is a variable that can be used under \( a_0 \), adding the restriction \( (a_0 = \{x\}) \), keeps the context consistent.

\textbf{\( \otimes_R \)}

We are only allowed to refine using \( \otimes_R \) when \( A_0 = B \otimes C \). Let \( \mathcal{X}' = \{(a_0 = a_1 \cup a_2), (a_1' = \{z\}), (a_1 = a_1'[\frac{a_2[id]}{z}]), (a_2' = \{w\}), (a_2 = a_2'[\frac{a_1[id]}{w}])\} \) and \( \Delta' = u_1 : [\Gamma_0]a_1B, u_2 : [\Gamma_0]a_2C \).

Then let \( M = \)

\[
\frac{X, X'|\Delta, \Delta'|\Gamma_0 \vdash id : \Gamma_0 \quad z : B \in \Gamma_0, z : B \quad a_1' = \{z\} \in X, X' \quad \Delta, \Delta'|\Gamma_0, z : B \vdash a_1' z : B \quad a_1 = a_1'[\frac{a_2[id]}{z}] \in X, X'}{X, X'|\Delta, \Delta'|\Gamma_0 \vdash a_1 z : B} \quad \text{MV}
\]

and \( N = \)

\[
\frac{X, X'|\Delta, \Delta'|\Gamma_0 \vdash id : \Gamma_0 \quad w : C \in \Gamma_0, w : C \quad a_2' = \{w\} \in X, X' \quad \Delta, \Delta'|\Gamma_0, w : C \vdash a_2' w : C \quad a_2 = a_2'[\frac{a_1[id]}{w}] \in X, X'}{X, X'|\Delta, \Delta'|\Gamma_0 \vdash a_2 w : C} \quad \text{MV}
\]
Then we have

\[ M \quad N \quad a = a_1 \cup a_2 \in \mathcal{X}, \mathcal{X}' \]

\[ \mathcal{X}, \mathcal{X}' | \Delta, \Delta' | \Gamma_0 \vdash_{a_0} \text{(let } z \text{ be } u_1[^{id}] \text{ in } z, \text{let } w \text{ be } u_2[^{id}] \text{ in } w) : B \otimes C \]

\[ \otimes R \]

\[ \otimes L \]

The proof assistant only allows us to apply a left rule on a variable \( x \) if \( a_0 \) has not already been set to something else inside of \( \mathcal{X} \), and if \( x \) is contained in the upper bound multiset of variables that \( a_0 \) can use and \( x : B \otimes C \in \Gamma_0 \). In that case we get:

Let \( \mathcal{X}' = \{(a_0[^{\{x_1,x_2\}\{x\}}]) = a'_0, (a'_0 = a''_0[^{a'_0[^{id}]\{z\}}]), (a''_0 = \{z\})\} \) and \( \Delta' = u_1 : \Gamma_0, x : B \otimes C, x_1 : B, x_2 : C | a_1, A_0 \).

Then let \( M = \)

\[ X, X' | \Delta, \Delta' | \Gamma_0, x_1, x_2 \vdash \text{id} : \Gamma_0, x_1, x_2 \]

\[ X, X' | \Delta, \Delta' | \Gamma_0, x_1, x_2, z : B \otimes C, \Delta' \vdash_{\lambda_z} : \Delta' \]

\[ X, X' | \Delta, \Delta' | \Gamma_0, x_1, x_2, z : B \otimes C | \lambda_z \text{ let } z \text{ be } u_1[^{id}] \text{ in } z : \Delta_0 \]

\[ \text{MV} \]

Then we have

\[ M \quad a_0[^{\{x_1,x_2\}\{x\}}] = a'_0 \in \mathcal{X}, \mathcal{X}' \]

\[ \mathcal{X}, \mathcal{X}' | \Delta, \Delta' | \Gamma_0 \vdash_{a_0} \text{let } (x_1, x_2) \text{ be } x \text{ in } \text{(let } z \text{ be } u_1[^{id}] \text{ in } z) : A_0 \]

\[ \otimes L \]

Since \( a_0 = \{x_1, ..., x_n\} \notin \mathcal{X} \), and \( x \) is a variable that can be used under \( a_0 \), adding the restriction that uses up \( x \) in \( a_0 \) by flipping it for \( x_1, x_2 \) in \( a'_0 \), keeps the context consistent.

After we have completed \( \mathcal{X}, \mathcal{X}' | \Delta, \Delta' | \Gamma_0 \vdash_{a_0} t : A_0 \) we use Corollary on it and \( \mathcal{X} | \Delta, u : [\Gamma_0]_{a_0} : A_0 | \Gamma \vdash_{a} e : A \) and we are done. \( \square \)
4.3. Implementation details.

In order to implement the proof assistant, we used OCaml. It became the language of choice because of its easy-to-define ADTs and its bigger popularity in the industry compared to Standard ML.

The project is broken down in multiple components:

1. A TermVar module used for storing and comparing Term, Meta and Resource variables.

2. A Syntax backbone module where types, terms and functions on them are defined.

3. A Typechecker module that is used to check if we have a valid term and a consistent context of restrictions that can identify all $\alpha$s.

4. The main module which keeps the tables of contexts and runs the proof assistant.

When the program starts, the context that the user enters is parsed and saved into a hashtable that maps term variables to their types. The intended type entered by the user is also parsed and saved as the type of the first metavariable, together with the context hashtable and a new resource variable. That resource variable is then a part of an equation that says that it has to use up all of the resources from the entered context, and the equation is saved in the restrictions context.
After this we are in a loop whose guard checks if our term doesn’t contain any metavariables in which case we exit the loop and are done if the term typechecks (with a consistent restrictions context).

If our term does contain metavariables, after the user selects a metavariable (goal) to work on, the proof assistant comes up with all of the useful information the user might need to construct a term: available variables and metavariables, type of the goal and applicable rules.

The refinement process works by replacing the metavariable in the term with the newly constructed term and updating the metavariable and restrictions context with the new metavariables and restrictions.
5. Conclusion

We have presented the process of building a proof assistant for propositional linear logic. In doing so, we have built two sequent calculi and showed their consistency. Because of the use of modal contexts and meta variables as well as the need for efficient splitting of linear contexts of variables, we introduced an implementation framework which delays important decisions like resource allocation. This allows the user to have more freedom in building a proof and adjust the resources available while building the proof. We chose linear logic as an example logic where these issues come up, but this framework can be used for many other substructural logics too.

This project can be further improved by adding types and terms for the quantifiable part of linear logic that we omitted, as well as dependent types. An in-editor implementation would also be a big step forward from the current terminal-based proof assistant.
Bibliography


